TMS320C2834x Delfino MCU

Silicon Errata

Literature Number: SPRZ267
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1 Introduction

This document describes the silicon updates to the functional specifications for the TMS320C2834x microcontrollers (MCUs).

The updates are applicable to:

- 179-ball MicroStar BGA™, ZHH Suffix
- 256-ball Plastic BGA, ZFE Suffix

2 Device and Development Tool Support Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all [TMS320] DSP devices and support tools. Each TMS320™ DSP commercial family member has one of three prefixes: TMX, TMP, or TMS (e.g., **TMS**320C28345). Texas Instruments recommends two of three possible prefix designators for its support tools: TMDX and TMDS. These prefixes represent evolutionary stages of product development from engineering prototypes (TMX/TMDX) through fully qualified production devices/tools (TMS/TMDS).

TMX Experimental device that is not necessarily representative of the final device's electrical specifications

TMP Final silicon die that conforms to the device's electrical specifications but has not completed quality and reliability verification

TMS Fully qualified production device

Support tool development evolutionary flow:

TMDX Development-support product that has not yet completed Texas Instruments internal qualification testing

TMDS Fully qualified development-support product

TMX and TMP devices and TMDX development-support tools are shipped against the following disclaimer:
"Developmental product is intended for internal evaluation purposes."

TMS devices and TMDS development-support tools have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

Predictions show that prototype devices (TMX or TMP) have a greater failure rate than the standard production devices. Texas Instruments recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the package type (for example, ZFE) and temperature range (for example, T).

3 Device Markings

Figure 1 provides an example of the 2834x device markings and defines each of the markings. The device revision can be determined by the symbols marked on the top of the package as shown in Table 1. Some prototype devices may have markings different from those illustrated. Figure 2 shows an example of the device nomenclature.

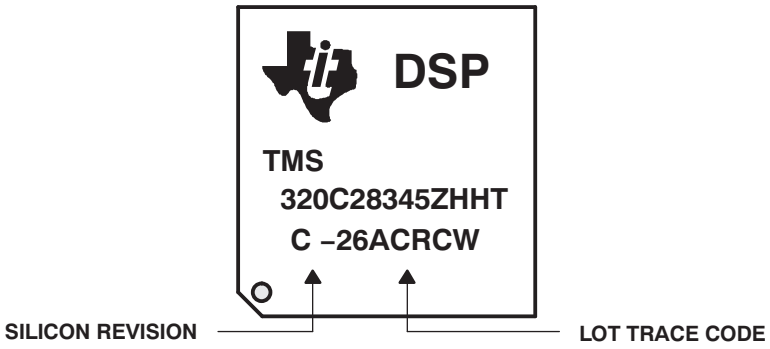


Figure 1. Example of Device Markings

Table 1. Determining Silicon Revision From Lot Trace Code (2834x devices)

SECOND LETTER IN PREFIX OF LOT TRACE CODE	SILICON REVISION	REVISION ID (0x0883)	COMMENTS
Blank (no second letter in prefix)	Indicates Revision 0	0x0000	This silicon revision is available as TMX.

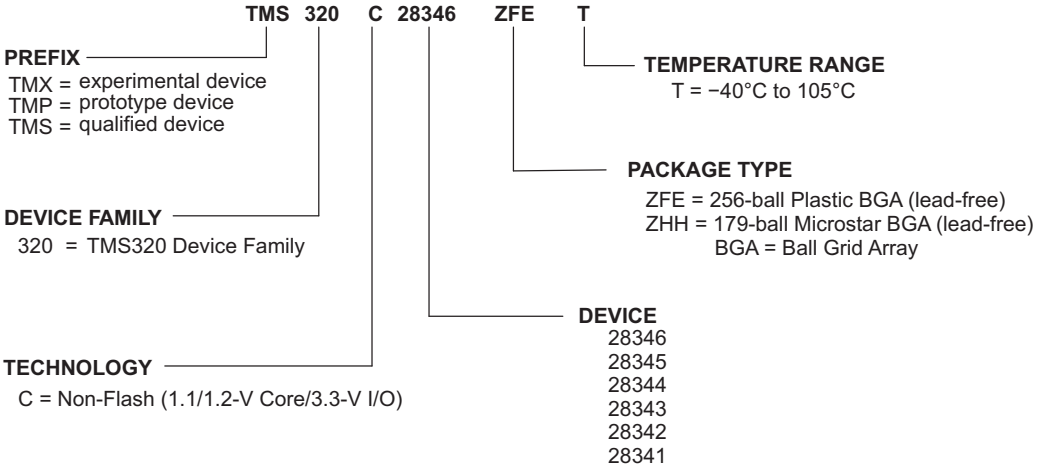


Figure 2. Example of Device Nomenclature

4 Rev 0 Known Design Marginality/Exceptions to Functional Specifications

Table 2. Advisory List for Rev 0 Silicon

Advisory — *Boot ROM - Incorrect MUX Configuration for Jump to XINTF x32*

Revision(s) Affected 0

Details The boot ROM incorrectly configures GPBMUX2 for peripheral operation instead of XD[31:16]. This issue affects the jump to XINTF x32 boot mode.

Workaround None. Use "Jump to XINTF x16 boot mode" instead.

Advisory — *Memory: Prefetching Beyond Valid Memory*

Revision(s) Affected 0

Details The C28x CPU prefetches instructions beyond those currently active in its pipeline. If the prefetch occurs past the end of valid memory, then the CPU may receive an invalid opcode.

Workaround The prefetch queue is 8x16 words in depth. Therefore, code should not come within 8 words of the end of valid memory. This restriction applies to all memory regions and all memory types (flash, OTP, SARAM, XINTF) on the device. Prefetching across the boundary between two valid memory blocks is all right.

Example 1: M1 ends at address 0x7FF and is not followed by another memory block. Code in M1 should be stored no farther than address 0x7F7. Addresses 0x7F8-0x7FF should not be used for code.

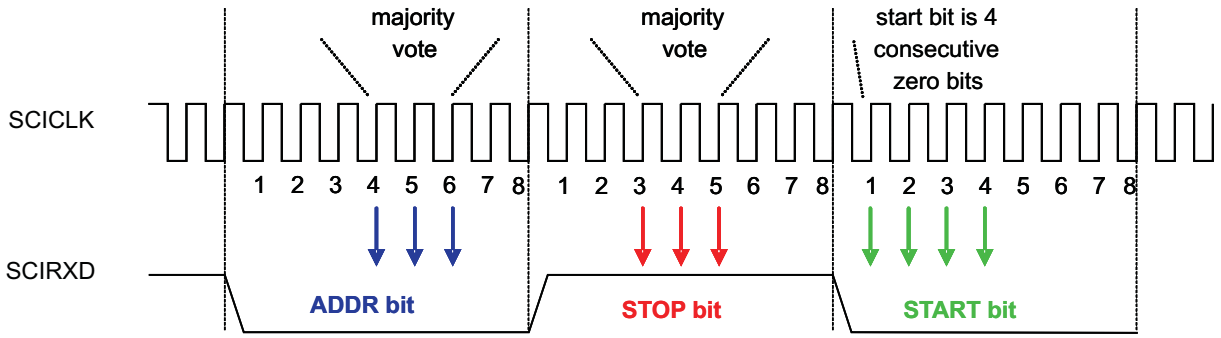
Example 2: M0 ends at address 0x3FF and valid memory (M1) follows it. Code in M0 can be stored up to and including address 0x3FF. Code can also cross into M1 up to and including address 0x7F7.

Advisory — *SCI: Incorrect Operation of SCI in Address Bit Mode*

Revision(s) Affected 0

Details SCI does not look for STOP bit after the ADDR bit. Instead, SCI starts looking for the start bit beginning on sub-sample 6 of the ADDR bit. Slow rise-time from ADDR to STOP bit can cause the false START bit to occur since the 4th sub-sample for the start bit may be sensed low.

Expected Operation:



Erroneous Operation:

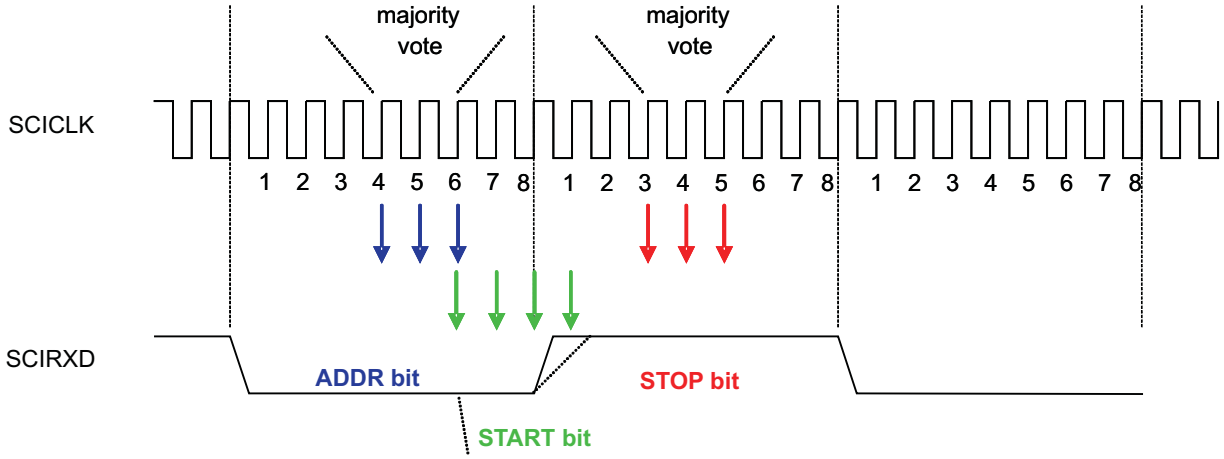


Figure 3. Difference Between Expected and Erroneous Operation of START Bit

Workaround(s) Program the baud rate of the SCI to be slightly slower than the actual. This will cause the 4th sub-sample of the false START bit to be delayed in time, and therefore occur more towards the middle of the STOP bit (away from the signal transition region). The amount of baud slowing needed depends on the rise-time of the signal in the system. Alternatively, IDLE mode of the SCI module may be used, if applicable.

Advisory *eCAN: Abort Acknowledge Bit Not Set*

Revision(s) Affected 0

Details

After setting a Transmission Request Reset (TRR) register bit to abort a message, there are some rare instances where the TRRn and TRSn bits will clear without setting the Abort Acknowledge (AAn) bit. The transmission itself is correctly aborted, but no interrupt is asserted and there is no indication of a pending operation.

In order for this rare condition to occur, all of the following conditions must happen:

1. The previous message was not successful, either because of lost arbitration or because no node on the bus was able to acknowledge it or because an error frame resulted from the transmission. The previous message need not be from the same mailbox in which a transmit abort is currently being attempted.
2. The TRRn bit of the mailbox should be set in a CPU cycle immediately following the cycle in which the TRSn bit was set. The TRSn bit remaining set due to incompletion of transmission satisfies this condition as well. i.e. the TRSn bit could have been set in the past, but the transmission remains incomplete.
3. The TRRn bit must be set in the exact SYSCLKOUT cycle where the CAN module is in idle state for one cycle. The CAN module is said to be in idle state when it is not in the process of receiving/transmitting data.

If these conditions occur, then the TRRn and TRSn bits for the mailbox will clear t_{clr} SYSCLKOUT cycles after the TRR bit is set where:

$$t_{clr} = [(\text{mailbox\_number}) * 2] + 3 \text{ SYSCLKOUT cycles}$$

The TAn and AAn bits will not be set if this condition occurs. Normally, either the TA or AA bit sets after the TRR bit goes to zero.

Workaround(s)

When this problem occurs, the TRRn and TRSn bits will clear within t_{clr} SYSCLKOUT cycles. To check for this condition, first disable the interrupts. Check the TRRn bit t_{clr} SYSCLKOUT cycles after setting the TRRn bit to make sure it is still set. A set TRRn bit indicates that the problem did not occur.

If the TRRn bit is cleared, it could be because of the normal end of a message and the corresponding TAn or AAn bit is set. Check both the TAn and AAn bits. If either one of the bits is set, then the problem did not occur. If they are both zero, then the problem did occur. Handle the condition like the interrupt service routine would except that the AAn bit does not need clearing now.

If the TAn or AAn bit is set, then the normal interrupt routine will happen when the interrupt is re-enabled.

Advisory *GPIO: GPIO Qualification*

Revision(s) Affected 0

Details If a GPIO pin is configured for "n" SYSCLKOUT cycle qualification period (where $1 \leq n \leq 510$) with "m" qualification samples (m = 3 or 6), it is possible that an input pulse of [n * m – (n – 1)] width may get qualified (instead of n * m). This depends upon the alignment of the asynchronous GPIO input signal with respect to the phase of the internal prescaled clock, and hence, is not deterministic. The probability of this kind of wrong qualification occurring is "1/n".

Worst-case example:

If n = 510, m = 6, a GPIO input width of (n * m) = 3060 SYSCLKOUT cycles is required to pass qualification. However, because of the issue described in this advisory, the minimum GPIO input width which may get qualified is [n * m – (n – 1)] = 3060 – 511 = 2549 SYSCLKOUT cycles.

Workaround(s) None. Ensure a sufficient margin is in the design for input qualification.

5 Documentation Support

For device-specific data sheets and related documentation, visit the TI web site at: http://www.ti.com.

To access documentation on the web site:

1. Go to http://www.ti.com
2. Click on *Microcontrollers (MCU)*
3. Under the heading *C2000™ High Performance 32-bit Controllers*, click on the appropriate device family.
4. Click on a device name and then click on the documentation type you prefer.

For further information regarding the 2834x devices, see the *TMS320C28346, TMS320C28345, TMS320C28344, TMS320C28343, TMS320C28342, TMS320C28341 Delfino Microcontrollers Data Manual* (literature number SPRS516).

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