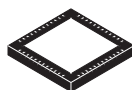




## MC9S08QE32 Series

Covers: MC9S08QE32 and  
MC9S08QE16

## MC9S08QE32



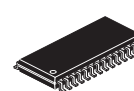
48-QFN  
Case 1314  
7 mm<sup>2</sup>



44-LQFP  
Case 824D



32-LQFP  
Case 873A  
7 mm<sup>2</sup>



28-SOIC  
Case 751F

### Features

- 8-Bit HCS08 Central Processor Unit (CPU)
  - Up to 50.33 MHz HCS08 CPU at 3.6 V to 2.4 V, 40 MHz CPU at 2.4 V to 2.1 V and 20 MHz CPU at 2.1 V to 1.8 V across temperature range of -40°C to 85°C
  - HC08 instruction set with added BGND instruction
  - Support for up to 32 interrupt/reset sources
- On-Chip Memory
  - Flash read/program/erase over full operating voltage and temperature
  - Random-access memory (RAM)
  - Security circuitry to prevent unauthorized access to RAM and flash contents
- Power-Saving Modes
  - Two very low power stop modes
  - Reduced power wait mode
  - Peripheral clock enable register can disable clocks to unused modules, thereby reducing currents; allows clocks to remain enabled to specific peripherals in stop3 mode.
  - Very low power external oscillator that can be used in run, wait, and stop modes to provide accurate clock source to real time counter.
  - 6  $\mu$ s typical wakeup time from stop3 mode
- Clock Source Options
  - Oscillator (XOSCVLP) — Loop-control Pierce oscillator; crystal or ceramic resonator range of 31.25 kHz to 38.4 kHz or 1 MHz to 16 MHz
  - Internal clock source (ICS) — Internal clock source module containing a frequency-locked-loop (FLL) controlled by internal or external reference; precision trimming of internal reference allows 0.2% resolution and 2% deviation over temperature and voltage; supports CPU frequencies from 4 kHz to 50.33 MHz.
- System Protection
  - Watchdog computer operating properly (COP) reset with option to run from dedicated 1 kHz internal clock source or bus clock.
  - Low-voltage warning with interrupt.
  - Low-voltage detection with reset or interrupt
  - Selectable trip points.
  - Illegal opcode detection with reset
  - Illegal address detection with reset
  - Flash block protection
- Development Support
  - Single-wire background debug interface
- Breakpoint capability to allow single breakpoint setting during in-circuit debugging (plus three breakpoints in on-chip debug module)
- On-chip in-circuit emulator (ICE) debug module containing three comparators and nine trigger modes. Eight deep FIFO for storing change-of-flow addresses and event-only data. Debug module supports both tag and force breakpoints
- Peripherals
  - **ADC** — 10-channel, 12-bit resolution; 2.5  $\mu$ s conversion time; automatic compare function; 1.7 mV/°C temperature sensor; internal bandgap reference channel; operation in stop3; fully functional from 3.6 V to 1.8 V
  - **ACMPx** — Two analog comparators with selectable interrupt on rising, falling, or either edge of comparator output; compare option to fixed internal bandgap reference voltage; outputs can be optionally routed to TPM module; operation in stop3
  - **SCIx** — Two serial communications interface modules with optional 13-bit break. Full duplex non-return to zero (NRZ); LIN master extended break generation; LIN slave extended break detection; wake on active edge.
  - **SPI** — One serial peripheral interface; full-duplex or single-wire bidirectional; double-buffered transmit and receive; master or slave mode; MSB-first or LSB-first shifting
  - **IIC** — One IIC; up to 100 kbps with maximum bus loading; multi-master operation; programmable slave address; interrupt driven byte-by-byte data transfer; supports broadcast mode and 10-bit addressing
  - **TPMx** — One 6-channel (TPM3) and two 3-channel (TPM1 and TPM2); selectable input capture, output compare, or buffered edge- or center-aligned PWM on each channel;
  - **RTC** — (Real-time counter) 8-bit modulus counter with binary or decimal based prescaler; external clock source for precise time base, time-of-day, calendar or task scheduling functions; free running on-chip low power oscillator (1 kHz) for cyclic wake-up without external components; runs in all MCU modes
- Input/Output
  - 40 GPIOs, including 1 output-only pin and 1 input-only pin
  - 16 KBI interrupts with selectable polarity
  - Hysteresis and configurable pull up device on all input pins; Configurable slew rate and drive strength on all output pins.
- Package Options
  - 48-pin QFN, 44-pin LQFP, 32-pin LQFP, 28-pin SOIC

This document contains information on a product under development. Freescale reserves the right to change or discontinue this product without notice.

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## Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

<http://freescale.com/>

The following revision history table summarizes changes contained in this document.

Revision	Date	Description of Changes
1	7/2/2008	Initial public released.
2	10/7/2008	Updated the Stop2 and Stop3 mode supply current, and $R_{IDD}$ in FEI mode with all modules on at 25.165 MHz in the <a href="#">Table 8</a> Supply Current Characteristics. Replaced the stop mode adders section from <a href="#">Table 8</a> with an individual <a href="#">Table 9</a> Stop Mode Adders with new specifications.
3	11/4/2008	Updated operating voltage in <a href="#">Table 7</a> .

## Related Documentation

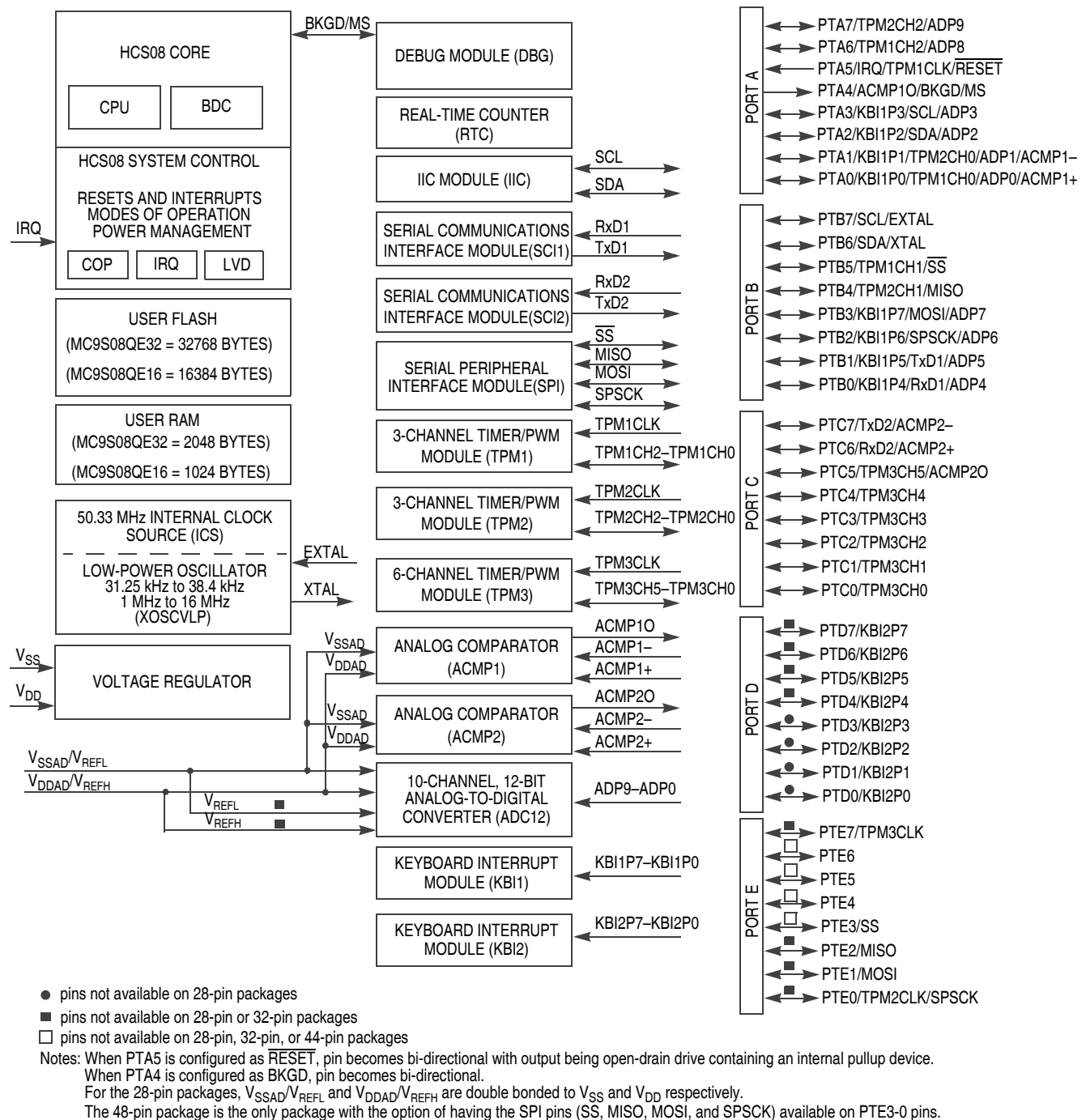
Find the most current versions of all documents at: <http://www.freescale.com>

### Reference Manual (MC9S08QE32RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

# 1 MCU Block Diagram

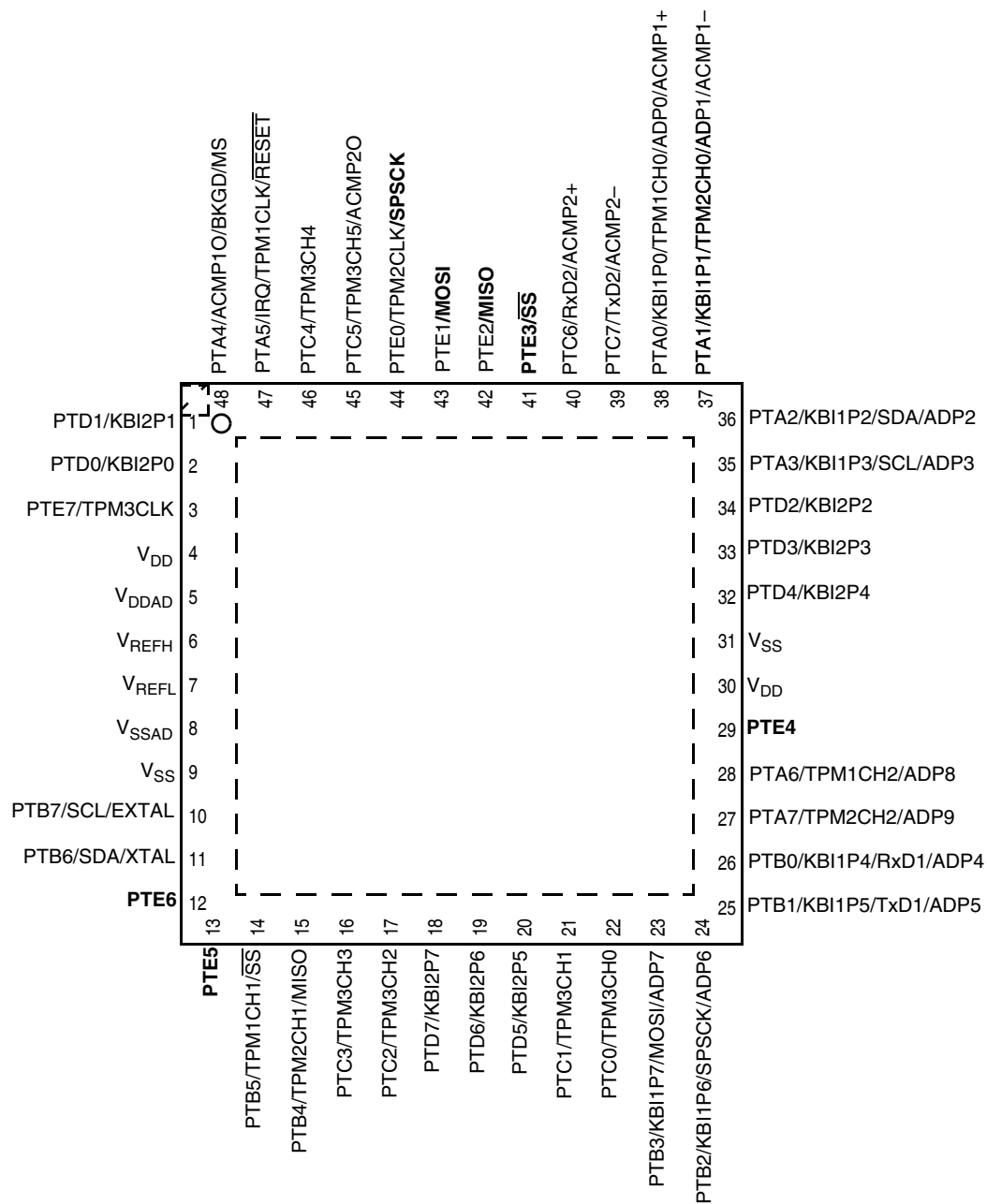
The block diagram, [Figure 1](#), shows the structure of the MC9S08QE32 MCU.



**Figure 1. MC9S08QE32 Series Block Diagram**

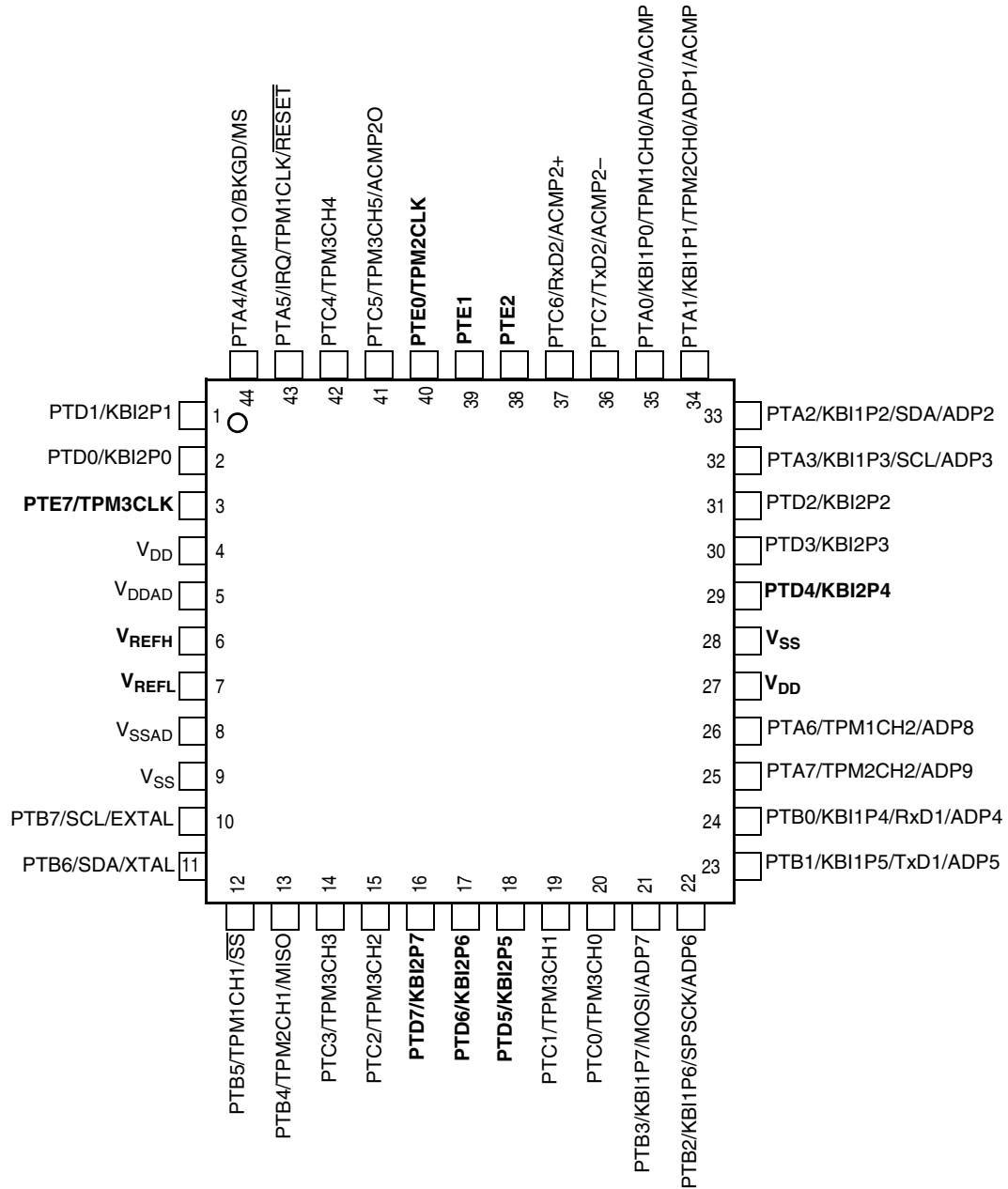
## 2 Pin Assignments

This section shows the pin assignments for the MC9S08QE32 series devices.



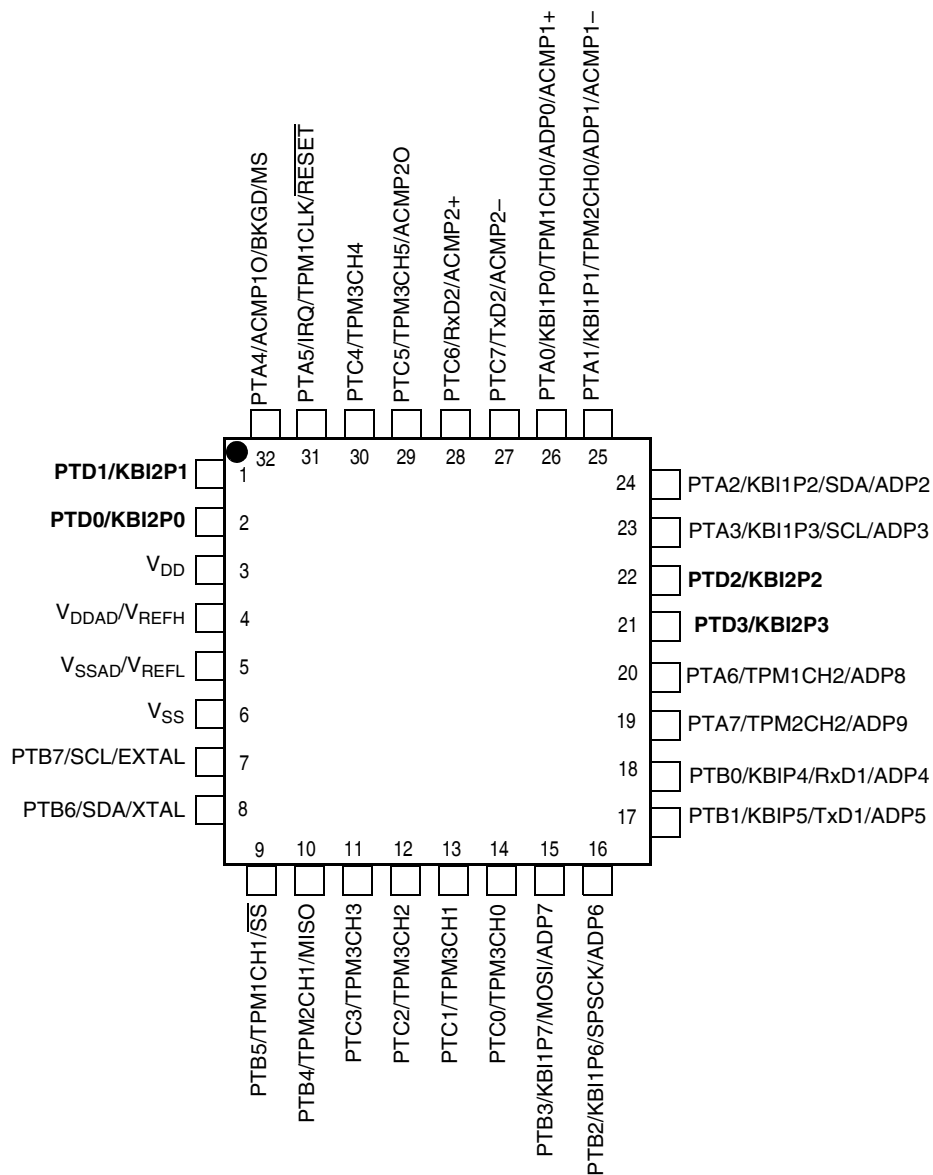
Pins in **bold** are lost in the next lower pin count package.

**Figure 2. 48-Pin QFN**



Pins in **bold** are lost in the next lower pin count package.

**Figure 3. 44-Pin LQFP**



Pins in **bold** are lost in the next lower pin count package.

**Figure 4. 32-Pin LQFP**

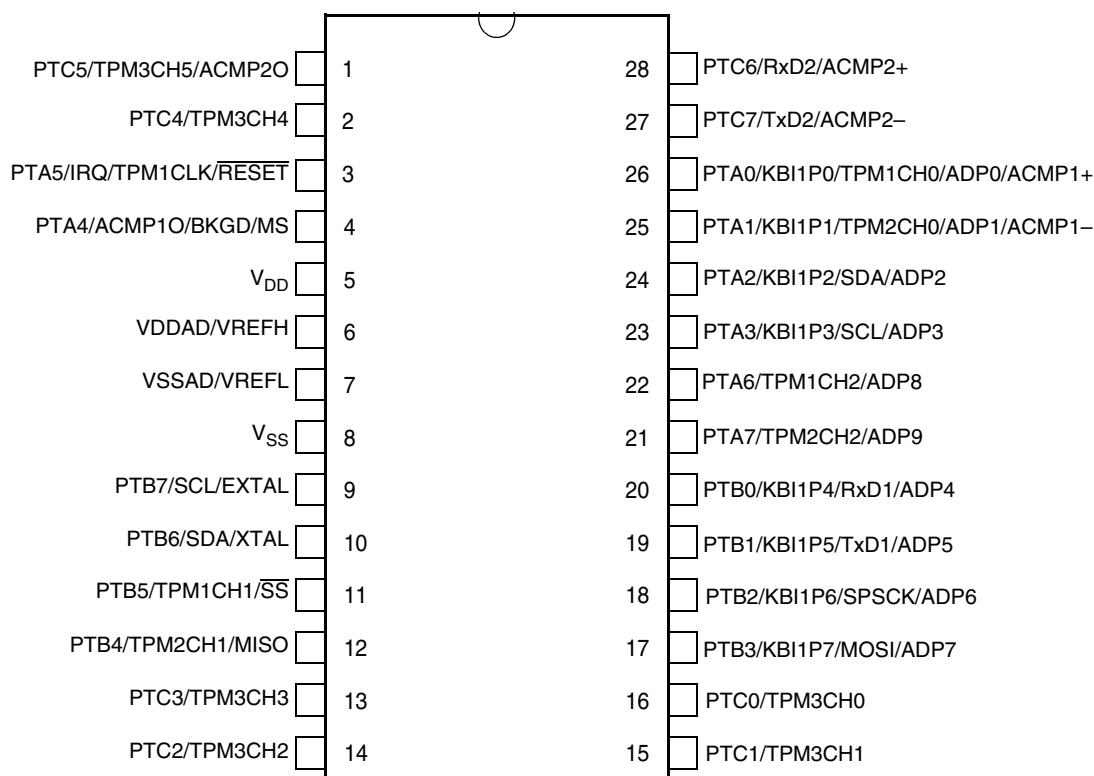


Figure 5. 28-Pin SOIC

Table 1. MC9S08QE32 Series Pin Assignment by Package and Pin Sharing Priority

Pin Number				<-- Lowest Priority --> Highest				
48	44	32	28	Port Pin	Alt 1	Alt 2	Alt 3	Alt 4
1	1	1	—	PTD1	KBI2P1			
2	2	2	—	PTD0	KBI2P0			
3	3	—	—	PTE7	TPM3CLK			
4	4	3	5					V <sub>DD</sub>
5	5	4	6					V <sub>DDAD</sub>
6	6							V <sub>REFH</sub>
7	7	5	7					V <sub>REFL</sub>
8	8							V <sub>SSAD</sub>
9	9	6	8					V <sub>SS</sub>
10	10	7	9	PTB7	SCL <sup>1</sup>			EXTAL
11	11	8	10	PTB6	SDA <sup>1</sup>			XTAL
12	—	—	—	PTE6				
13	—	—	—	PTE5				
14	12	9	11	PTB5	TPM1CH1	SS <sup>2</sup>		
15	13	10	12	PTB4	TPM2CH1	MISO <sup>2</sup>		
16	14	11	13	PTC3	TPM3CH3			
17	15	12	14	PTC2	TPM3CH2			
18	16	—	—	PTD7	KBI2P7			

Table 1. MC9S08QE32 Series Pin Assignment by Package and Pin Sharing Priority (continued)

Pin Number				<-- Lowest Priority --> Highest				
48	44	32	28	Port Pin	Alt 1	Alt 2	Alt 3	Alt 4
19	17	—	—	PTD6	KBI2P6			
20	18	—	—	PTD5	KBI2P5			
21	19	13	15	PTC1	TPM3CH1			
22	20	14	16	PTC0	TPM3CH0			
23	21	15	17	PTB3	KBI1P7	MOSI <sup>2</sup>		ADP7
24	22	16	18	PTB2	KBI1P6	SPSCK <sup>2</sup>		ADP6
25	23	17	19	PTB1	KBI1P5	TxD1		ADP5
26	24	18	20	PTB0	KBI1P4	RxD1		ADP4
27	25	19	21	PTA7	TPM2CH2			ADP9
28	26	20	22	PTA6	TPM1CH2			ADP8
29	—	—	—	PTE4				
30	27	—	—					V <sub>DD</sub>
31	28	—	—					V <sub>SS</sub>
32	29	—	—	PTD4	KBI2P4			
33	30	21	—	PTD3	KBI2P3			
34	31	22	—	PTD2	KBI2P2			
35	32	23	23	PTA3	KBI1P3	SCL <sup>1</sup>		ADP3
36	33	24	24	PTA2	KBI1P2	SDA <sup>1</sup>		ADP2
37	34	25	25	PTA1	KBI1P1	TPM2CH0	ADP1 <sup>3</sup>	ACMP1— <sup>3</sup>
38	35	26	26	PTA0	KBI1P0	TPM1CH0	ADP0 <sup>3</sup>	ACMP1+ <sup>3</sup>
39	36	27	27	PTC7	TxD2			ACMP2—
40	37	28	28	PTC6	RxD2			ACMP2+
41	—	—	—	PTE3	$\overline{SS}$ <sup>2</sup>			
42	38	—	—	PTE2	MISO <sup>2</sup>			
43	39	—	—	PTE1	MOSI <sup>2</sup>			
44	40	—	—	PTE0	TPM2CLK	SPSCK <sup>2</sup>		
45	41	29	1	PTC5	TPM3CH5			ACMP2O
46	42	30	2	PTC4	TPM3CH4			
47	43	31	3	PTA5	IRQ	TPM1CLK	$\overline{RESET}$	
48	44	32	4	PTA4	ACMP1O	BKGD	MS	

<sup>1</sup> IIC pins, SCL and SDA can be repositioned using IICPS in SOPT2; default reset locations are PTA3 and PTA2.

<sup>2</sup> SPI pins ( $\overline{SS}$ , MISO, MOSI, and SPSCK) can be repositioned using SPIPS in SOPT2. Default locations are PTB5, PTB4, PTB3, and PTB2.

<sup>3</sup> If ADC and ACMP1 are enabled, both modules will have access to the pin.



## 3 Electrical Characteristics

### 3.1 Introduction

This section contains electrical and timing specifications for the MC9S08QE32 series of microcontrollers available at the time of publication.

### 3.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

**Table 2. Parameter Classifications**

<b>P</b>	Those parameters are guaranteed during production testing on each individual device.
<b>C</b>	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
<b>T</b>	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
<b>D</b>	Those parameters are derived mainly from simulations.

#### NOTE

The classification is shown in the column labeled “C” in the parameter tables where appropriate.

### 3.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in [Table 3](#) may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{DD}$ ) or the programmable pull-up resistor associated with the pin is enabled.

Table 3. Absolute Maximum Ratings

Rating	Symbol	Value	Unit
Supply voltage	$V_{DD}$	-0.3 to +3.8	V
Maximum current into $V_{DD}$	$I_{DD}$	120	mA
Digital input voltage	$V_{In}$	-0.3 to $V_{DD} + 0.3$	V
Instantaneous maximum current Single pin limit (applies to all port pins) <sup>1, 2, 3</sup>	$I_D$	$\pm 25$	mA
Storage temperature range	$T_{stg}$	-55 to 150	°C

<sup>1</sup> Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive ( $V_{DD}$ ) and negative ( $V_{SS}$ ) clamp voltages, then use the larger of the two resistance values.

<sup>2</sup> All functional non-supply pins, except for PTA5 are internally clamped to  $V_{SS}$  and  $V_{DD}$ .

<sup>3</sup> Power supply must maintain regulation within operating  $V_{DD}$  range during instantaneous and operating maximum current conditions. If positive injection current ( $V_{In} > V_{DD}$ ) is greater than  $I_{DD}$ , the injection current may flow out of  $V_{DD}$  and could result in external power supply going out of regulation. Ensure external  $V_{DD}$  load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).

### 3.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take  $P_{I/O}$  into account in power calculations, determine the difference between actual pin voltage and  $V_{SS}$  or  $V_{DD}$  and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and  $V_{SS}$  or  $V_{DD}$  will be very small.

Table 4. Thermal Characteristics

Rating	Symbol	Value	Unit
Operating temperature range (packaged)	T <sub>A</sub>	T <sub>L</sub> to T <sub>H</sub> −40 to 85	°C
Maximum junction temperature	T <sub>JM</sub>	95	°C
Thermal resistance Single-layer board			
48-pin QFN	θ <sub>JA</sub>	81	°C/W
44-pin LQFP		68	
32-pin LQFP		66	
28-pin SOIC		57	
Thermal resistance Four-layer board			
48-pin QFN	θ <sub>JA</sub>	26	°C/W
44-pin LQFP		46	
32-pin LQFP		54	
28-pin SOIC		42	

The average chip-junction temperature ( $T_J$ ) in °C can be obtained from:

$$T_J = T_A + (P_D \times \theta_{JA}) \quad \text{Eqn. 1}$$

where:

$T_A$  = Ambient temperature, °C

$\theta_{JA}$  = Package thermal resistance, junction-to-ambient, °C/W

$P_D = P_{int} + P_{I/O}$

$P_{int} = I_{DD} \times V_{DD}$ , Watts — chip internal power

$P_{I/O}$  = Power dissipation on input and output pins — user determined

For most applications,  $P_{I/O} \ll P_{int}$  and can be neglected. An approximate relationship between  $P_D$  and  $T_J$  (if  $P_{I/O}$  is neglected) is:

$$P_D = K \div (T_J + 273^\circ\text{C}) \quad \text{Eqn. 2}$$

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_A + 273^\circ\text{C}) + \theta_{JA} \times (P_D)^2 \quad \text{Eqn. 3}$$

where K is a constant pertaining to the particular part. K can be determined from equation 3 by measuring  $P_D$  (at equilibrium) for a known  $T_A$ . Using this value of K, the values of  $P_D$  and  $T_J$  can be obtained by solving Equation 1 and Equation 2 iteratively for any value of  $T_A$ .

### 3.5 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions must be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits. During the device qualification ESD stresses were performed for the human body model (HBM), the machine model (MM) and the charge device model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

**Table 5. ESD and Latch-up Test Conditions**

Model	Description	Symbol	Value	Unit
Human Body	Series resistance	R1	1500	$\Omega$
	Storage capacitance	C	100	pF
	Number of pulses per pin	—	3	
Machine	Series resistance	R1	0	$\Omega$
	Storage capacitance	C	200	pF
	Number of pulses per pin	—	3	
Latch-up	Minimum input voltage limit		-2.5	V
	Maximum input voltage limit		7.5	V

**Table 6. ESD and Latch-Up Protection Characteristics**

No.	Rating <sup>1</sup>	Symbol	Min	Max	Unit
1	Human body model (HBM)	V <sub>HBM</sub>	±2000	—	V
2	Machine model (MM)	V <sub>MM</sub>	±200	—	V
3	Charge device model (CDM)	V <sub>CDM</sub>	±500	—	V
4	Latch-up current at T <sub>A</sub> = 85°C	I <sub>LAT</sub>	±100	—	mA

<sup>1</sup> Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

### 3.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 7. DC Characteristics

Num	C	Characteristic	Symbol	Condition	Min	Typical <sup>1</sup>	Max	Unit
1		Operating Voltage <div>V<sub>DD</sub> rising V<sub>DD</sub> falling</div>			2.0 1.8	—	3.6	V
2	C	Output high voltage <sup>2</sup> <div>All I/O pins, low-drive strength</div>	V <sub>OH</sub>	1.8 V, I <sub>Load</sub> = −2 mA	V <sub>DD</sub> − 0.5	—	—	V
	P	2.7 V, I <sub>Load</sub> = −10 mA		V <sub>DD</sub> − 0.5	—	—		
	T	2.3 V, I <sub>Load</sub> = −6 mA		V <sub>DD</sub> − 0.5	—	—		
	C	1.8V, I <sub>Load</sub> = −3 mA		V <sub>DD</sub> − 0.5	—	—		
3	D	Output high current Max total I <sub>OH</sub> for all ports	I <sub>OHT</sub>		—	—	100	mA
4	C	Output low voltage <div>All I/O pins, low-drive strength</div>	V <sub>OL</sub>	1.8 V, I <sub>Load</sub> = 2 mA	—	—	0.5	V
	P	2.7 V, I <sub>Load</sub> = 10 mA		—	—	0.5		
	T	2.3 V, I <sub>Load</sub> = 6 mA		—	—	0.5		
	C	1.8 V, I <sub>Load</sub> = 3 mA		—	—	0.5		
5	D	Output low current Max total I <sub>OL</sub> for all ports	I <sub>OLT</sub>		—	—	100	mA
6	P	Input high voltage all digital inputs	V <sub>IH</sub>	V <sub>DD</sub> > 2.3 V	0.70 x V <sub>DD</sub>	—	—	V
	C			V <sub>DD</sub> ≤ 1.8 V	0.85 x V <sub>DD</sub>	—	—	
7	P	Input low voltage all digital inputs	V <sub>IL</sub>	V <sub>DD</sub> > 2.7 V	—	—	0.35 x V <sub>DD</sub>	
	C			V <sub>DD</sub> ≤ 1.8 V	—	—	0.30 x V <sub>DD</sub>	
8	C	Input hysteresis all digital inputs	V <sub>hys</sub>		0.06 x V <sub>DD</sub>	—	—	mV
9	P	Input leakage current all input only pins (Per pin)	I <sub>IIn</sub>	V <sub>In</sub> = V <sub>DD</sub> or V <sub>SS</sub>	—	5	1000	nA
10	P	Hi-Z (off-state) leakage current all input/output (per pin)	I <sub>IOZ</sub>	V <sub>In</sub> = V <sub>DD</sub> or V <sub>SS</sub>	—	5	1000	nA
11	P	Pullup, Pulldown resistors all digital inputs, when enabled	R <sub>PU</sub> , R <sub>PD</sub>		17.5	—	52.5	kΩ
12	D	DC injection current <sup>3, 4, 5</sup> Single pin limit Total MCU limit, includes sum of all stressed pins	I <sub>IC</sub>	V <sub>IN</sub> < V <sub>SS</sub> , V <sub>IN</sub> > V <sub>DD</sub>	−0.2	—	0.2	mA
					−5	—	5	mA
13	C	Input Capacitance, all pins	C <sub>In</sub>		—	—	8	pF
14	C	RAM retention voltage	V <sub>RAM</sub>		—	0.6	1.0	V
15	C	POR re-arm voltage <sup>6</sup>	V <sub>POR</sub>		0.9	1.4	2.0	V
16	D	POR re-arm time	t <sub>POR</sub>		10	—	—	μs
17	P	Low-voltage detection threshold — high range	V <sub>LVDH</sub>	V <sub>DD</sub> falling V <sub>DD</sub> rising	2.11 2.16	2.16 2.21	2.22 2.27	V
18	P	Low-voltage detection threshold — low range	V <sub>LVDL</sub>	V <sub>DD</sub> falling V <sub>DD</sub> rising	1.80 1.88	1.82 1.90	1.91 1.99	V

Table 7. DC Characteristics (continued)

Num	C	Characteristic	Symbol	Condition	Min	Typical <sup>1</sup>	Max	Unit
19	P	Low-voltage warning threshold — high range	$V_{LVWH}$	$V_{DD}$ falling $V_{DD}$ rising	2.36 2.36	2.46 2.46	2.56 2.56	V
20	P	Low-voltage warning threshold — low range	$V_{LVWL}$	$V_{DD}$ falling $V_{DD}$ rising	2.11 2.16	2.16 2.21	2.22 2.27	V
21	C	Low-voltage inhibit reset/recover hysteresis	$V_{hys}$		—	80	—	mV
22	P	Bandgap Voltage Reference <sup>7</sup>	$V_{BG}$		1.15	1.17	1.18	V

<sup>1</sup> Typical values are measured at 25°C. Characterized, not tested

<sup>2</sup> As the supply voltage rises, the LVD circuit will hold the MCU in reset until the supply has risen above  $V_{LVDL}$ .

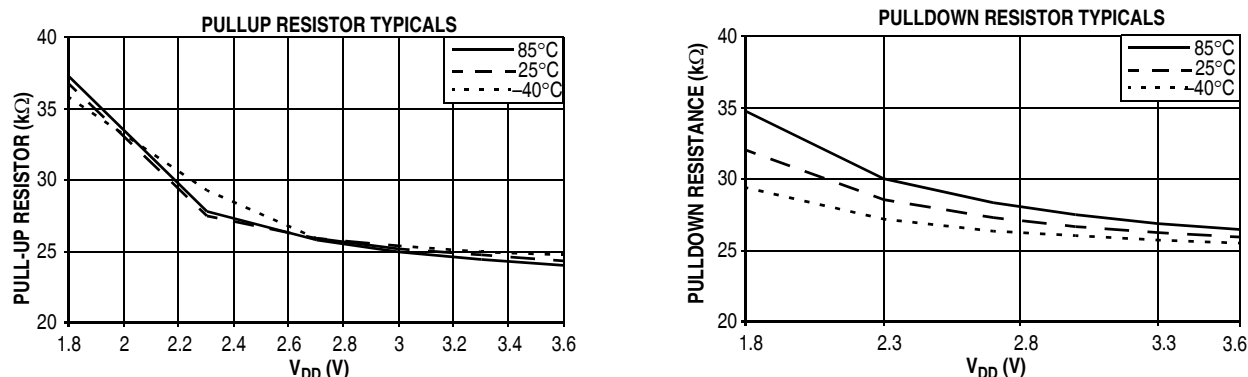
<sup>3</sup> All functional non-supply pins, except for PTA5 are internally clamped to  $V_{SS}$  and  $V_{DD}$ .

<sup>4</sup> Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.

<sup>5</sup> Power supply must maintain regulation within operating  $V_{DD}$  range during instantaneous and operating maximum current conditions. If positive injection current ( $V_{in} > V_{DD}$ ) is greater than  $I_{DD}$ , the injection current may flow out of  $V_{DD}$  and could result in external power supply going out of regulation. Ensure external  $V_{DD}$  load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

<sup>6</sup> Maximum is highest voltage that POR is guaranteed.

<sup>7</sup> Factory trimmed at  $V_{DD} = 3.0$  V, Temp = 25°C

Figure 6. Pullup and Pulldown Typical Resistor Values ( $V_{DD} = 3.0$  V)

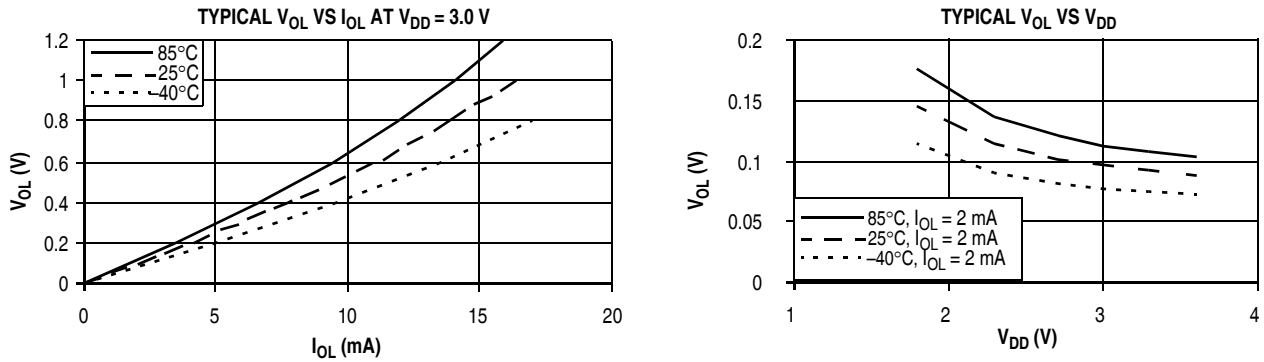


Figure 7. Typical Low-Side Driver (Sink) Characteristics — Low Drive (PTxDSn = 0)

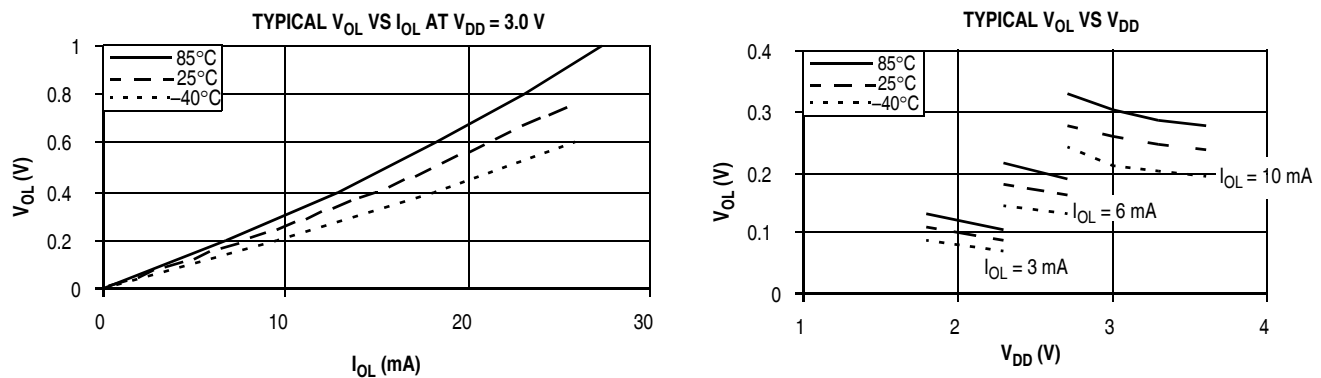


Figure 8. Typical Low-Side Driver (Sink) Characteristics — High Drive (PTxDSn = 1)

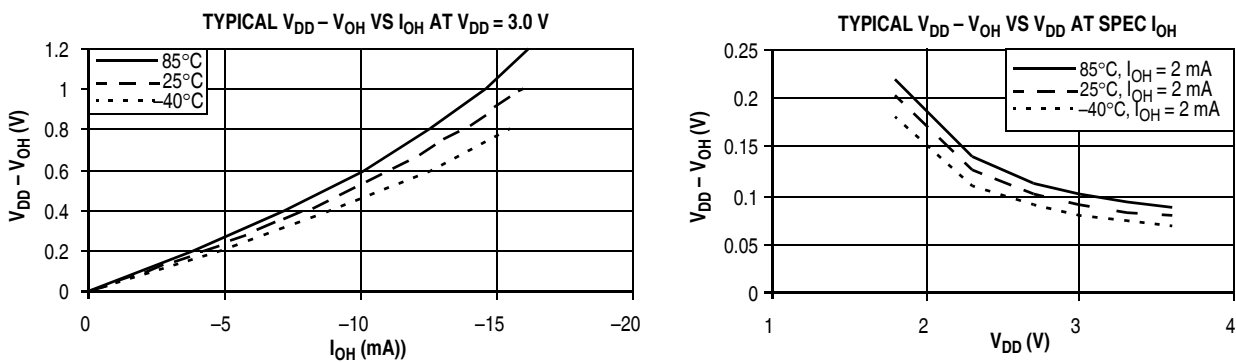


Figure 9. Typical High-Side (Source) Characteristics — Low Drive (PTxDSn = 0)

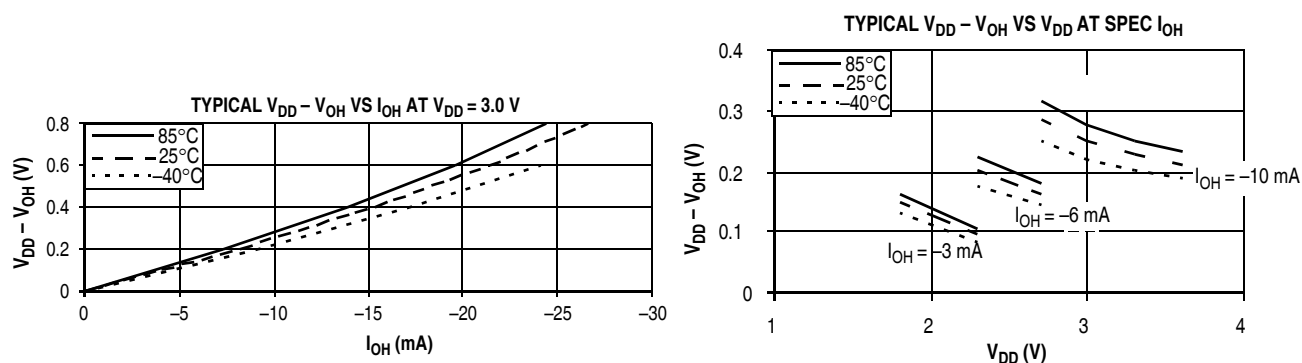


Figure 10. Typical High-Side (Source) Characteristics — High Drive (PTxDSn = 1)

### 3.7 Supply Current Characteristics

This section includes information about power supply current in various operating modes.

Table 8. Supply Current Characteristics

Num	C	Parameter	Symbol	Bus Freq	V <sub>DD</sub> (V)	Typical <sup>1</sup>	Max	Unit	Temp (°C)
1	P	Run supply current FEI mode, all modules on	R <sub>I</sub> DD	25.165 MHz	3	13	14	mA	-40 to 25
	P					14	15		85
	T					13.75	—	mA	-40 to 85
	T					5.59	—		
	T					1.03	—		
2	C	Run supply current FEI mode, all modules off	R <sub>I</sub> DD	25.165 MHz	3	11.5	12.3	mA	-40 to 85
	T			20 MHz		9.5	—		
	T			8 MHz		4.6	—		
	T			1 MHz		1.0	—		
3	T	Run supply current LPRS=0, all modules off	R <sub>I</sub> DD	16 kHz FBILP	3	152	—	μA	-40 to 85
	T			16 kHz FBELP		115	—		
4	T	Run supply current LPRS=1, all modules off, running from Flash	R <sub>I</sub> DD	16 kHz FBELP	3	21.9	—	μA	-40 to 85
	T	Run supply current LPRS=1, all modules off, running from RAM				7.3	—		
5	C	Wait mode supply current FEI mode, all modules off	W <sub>I</sub> DD	25.165 MHz	3	5.74	6.00	mA	-40 to 85
	T			20 MHz		4.57	—		
	T			8 MHz		2	—		
	T			1 MHz		0.73	—		



Table 8. Supply Current Characteristics (continued)

Num	C	Parameter		Symbol	Bus Freq	V <sub>DD</sub> (V)	Typical <sup>1</sup>	Max	Unit	Temp (°C)
6	P	Stop2 mode supply current		S2I <sub>DD</sub>	—	3	0.35	0.65	μA	–40 to 25°C
	C				—		0.8	1.0		70°C
	P				—		2.0	4.5		85°C
	C				—	2	0.25	0.50		–40 to 25°C
	C				—		0.65	0.85		70°C
	C				—		1.5	3.5		85°C
7	P	Stop3 mode supply current no clocks active		S3I <sub>DD</sub>	—	3	0.45	1.00	μA	–40 to 25°C
	C				—		1.5	2.3		70°C
	P				—		4	8		85°C
	C				—	2	0.35	0.70		–40 to 25°C
	C				—		1	2		70°C
	C				—		3.5	6.0		85°C
8	T	Low power mode adders:	EREFSTEN=1		32 kHz	3	500	—	nA	–40 to 85
9	T		IREFSTEN=1		32 kHz		70	—	μA	
10	T		TPM PWM		100 Hz		12	—	μA	
11	T		SCI, SPI, or IIC		300 bps		15	—	μA	
12	T		RTC using LPO		1 kHz		200	—	nA	
13	T		RTC using ICSERCLK		32 kHz		1	—	μA	
14	T		LVD		n/a		100	—	μA	
15	T		ACMP		n/a		20	—	μA	

<sup>1</sup> Data in Typical column was characterized at 3.0 V, 25°C or is typical recommended value.

Table 9. Stop Mode Adders

Num	C	Parameter	Condition	Temperature				Units
				–40°C	25°C	70°C	85°C	
1	T	LPO	—	50	75	100	150	nA
2	T	EREFSTEN	RANGE = HGO = 0	1000	1000	1100	1500	nA
3	T	IREFSTEN <sup>1</sup>	—	63	70	77	81	μA
4	T	RTC	Does not include clock source current	50	75	100	150	nA
5	T	LVD <sup>1</sup>	LVDSE = 1	90	100	110	115	μA
6	T	ACMP <sup>1</sup>	Not using the bandgap (BGBE = 0)	18	20	22	23	μA
7	T	ADC <sup>1</sup>	ADLPC = ADLSMP = 1 Not using the bandgap (BGBE = 0)	95	106	114	120	μA

<sup>1</sup> Not available in stop2 mode.

### 3.8 External Oscillator (XOSCVLP) Characteristics

Reference [Figure 11](#) and [Figure 12](#) for crystal or resonator circuits.

**Table 10. XOSC and ICS Specifications (Temperature Range = –40 to 85°C Ambient)**

Num	C	Characteristic	Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0) High range (RANGE = 1), high gain (HGO = 1) High range (RANGE = 1), low power (HGO = 0)	$f_{lo}$ $f_{hi}$ $f_{hi}$	32 1 1	— — —	38.4 16 8	kHz MHz MHz
2	D	Load capacitors Low range (RANGE=0), low power (HGO=0) Other oscillator settings	$C_1$ $C_2$	See Note <sup>2</sup> See Note <sup>3</sup>			
3	D	Feedback resistor Low range, low power (RANGE=0, HGO=0) <sup>2</sup> Low range, High Gain (RANGE=0, HGO=1) High range (RANGE=1, HGO=X)	$R_F$	— — —	— 10 1	— — —	MΩ
4	D	Series resistor — Low range, low power (RANGE = 0, HGO = 0) <sup>2</sup> Low range, high gain (RANGE = 0, HGO = 1) High range, low power (RANGE = 1, HGO = 0) High range, high gain (RANGE = 1, HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	$R_S$	— — — — — — —	— 100 0 0 0 0 0	— — — 0 10 20	kΩ
5	C	Crystal start-up time <sup>4</sup> Low range, low power Low range, high power High range, low power High range, high power	$t_{CSTL}$ $t_{CSTH}$	— — — —	200 400 5 15	— — — —	ms
6	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE mode FBE or FBELP mode	$f_{extal}$	0.03125 0	— —	40 40	MHz MHz

<sup>1</sup> Data in Typical column is characterized at 3.0 V, 25°C or is typical recommended value.

<sup>2</sup> Load capacitors ( $C_1, C_2$ ), feedback resistor ( $R_F$ ) and series resistor ( $R_S$ ) are incorporated internally when RANGE=HGO=0.

<sup>3</sup> See crystal or resonator manufacturer's recommendation.

<sup>4</sup> Proper PC board layout procedures must be followed to achieve specifications.

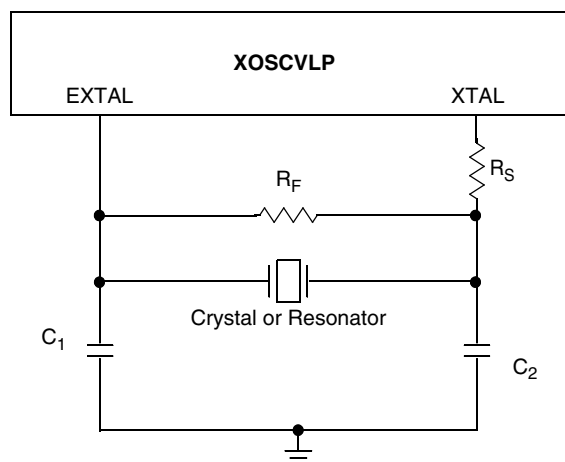


Figure 11. Typical Crystal or Resonator Circuit: High Range and Low Range/High Gain

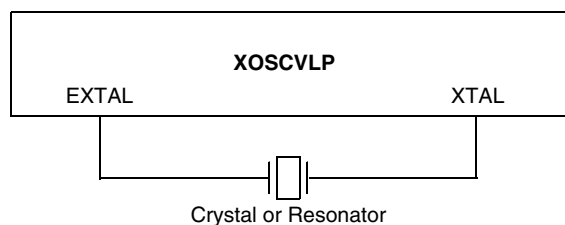


Figure 12. Typical Crystal or Resonator Circuit: Low Range/Low Power

### 3.9 Internal Clock Source (ICS) Characteristics

Table 11. ICS Frequency Specifications (Temperature Range =  $-40$  to  $85^{\circ}\text{C}$  Ambient)

Num	C	Characteristic		Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	C	Average internal reference frequency - untrimmed		$f_{\text{int\_ut}}$	—	32.768	—	kHz
2	P	Average internal reference frequency - trimmed		$f_{\text{int\_t}}$	31.25	—	39.06	kHz
3	T	Internal reference start-up time		$t_{\text{IRST}}$	—	60	100	$\mu\text{s}$
4	P	DCO output frequency trimmed <sup>2</sup>	Low range (DFR=00)	$f_{\text{dco\_u}}$	16	—	20	MHz
	P		Mid range (DFR=01)		32	—	40	
	P		High range (DFR=10)		48	—	60	
5	P	DCO output frequency <sup>2</sup> Reference = 32768 Hz and DMX32 = 1	Low range (DFR=00)	$f_{\text{dco\_DMX32}}$	—	19.92	—	MHz
	P		Mid range (DFR=01)		—	39.85	—	
	P		High range (DFR=10)		—	59.77	—	
6	C	Resolution of trimmed DCO output frequency at fixed voltage and temperature (using FTRIM)		$\Delta f_{\text{dco\_res\_t}}$	—	$\pm 0.1$	$\pm 0.2$	$\%f_{\text{dco}}$
7	C	Resolution of trimmed DCO output frequency at fixed voltage and temperature (not using FTRIM)		$\Delta f_{\text{dco\_res\_t}}$	—	$\pm 0.2$	$\pm 0.4$	$\%f_{\text{dco}}$

Table 11. ICS Frequency Specifications (Temperature Range = -40 to 85°C Ambient) (continued)

Num	C	Characteristic	Symbol	Min	Typical <sup>1</sup>	Max	Unit
8	C	Total deviation of trimmed DCO output frequency over voltage and temperature	$\Delta f_{dco\_t}$	—	+ 0.5 -1.0	±2	% $f_{dco}$
9	C	Total deviation of trimmed DCO output frequency over fixed voltage and temperature range of 0°C to 70 °C	$\Delta f_{dco\_t}$	—	± 0.5	±1	% $f_{dco}$
10	C	FLL acquisition time <sup>3</sup>	$t_{Acquire}$	—	—	1	ms
11	C	Long term jitter of DCO output clock (averaged over 2-ms interval) <sup>4</sup>	$C_{Jitter}$	—	0.02	0.2	% $f_{dco}$

<sup>1</sup> Data in Typical column is characterized at 3.0 V, 25 °C or is typical recommended value.

<sup>2</sup> The resulting bus clock frequency should not exceed the maximum specified bus clock frequency of the device.

<sup>3</sup> This specification applies to any time the FLL reference source or reference divider is changed, trim value changed or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

<sup>4</sup> Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum  $f_{Bus}$ . Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via  $V_{DD}$  and  $V_{SS}$  and variation in crystal oscillator frequency increase the  $C_{Jitter}$  percentage for a given interval.

## 3.10 AC Characteristics

This section describes timing characteristics for each peripheral system.

### 3.10.1 Control Timing

Table 12. Control Timing

Num	C	Rating	Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	D	Bus frequency ( $t_{cyc} = 1/f_{Bus}$ ) $V_{DD} \leq 2.1V$ $2.1 < V_{DD} \leq 2.4V$ $V_{DD} > 2.4Vs$	$f_{Bus}$	DC	—	10 20 25.165	MHz
2	D	Internal low power oscillator period	$t_{LPO}$	700	—	1300	μs
3	D	External reset pulse width <sup>2</sup>	$t_{extrst}$	100	—	—	ns
4	D	Reset low drive	$t_{rstdrv}$	$34 \times t_{cyc}$	—	—	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	$t_{MSSU}$	500	—	—	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes <sup>3</sup>	$t_{MSH}$	100	—	—	μs
7	D	IRQ pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>4</sup>	$t_{LIH}, t_{HIL}$	100 $1.5 \times t_{cyc}$	— —	— —	ns

Table 12. Control Timing (continued)

Num	C	Rating	Symbol	Min	Typical <sup>1</sup>	Max	Unit
8	D	Keyboard interrupt pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>5</sup>	$t_{\text{LIH}}, t_{\text{HIL}}$	100 $1.5 \times t_{\text{cyc}}$	— —	— —	ns
9	C	Port rise and fall time — Low output drive (PTxDS = 0) (load = 50 pF) <sup>5</sup> Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	$t_{\text{Rise}}, t_{\text{Fall}}$	— —	8 31	— —	ns
		Port rise and fall time — High output drive (PTxDS = 1) (load = 50 pF) Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	$t_{\text{Rise}}, t_{\text{Fall}}$	— —	7 24	— —	ns
10	C	Voltage regulator recovery time	$t_{\text{VRR}}$	—	4	—	μs

<sup>1</sup> Typical values are based on characterization data at  $V_{\text{DD}} = 3.0\text{V}$ ,  $25^\circ\text{C}$  unless otherwise stated.

<sup>2</sup> This is the shortest pulse that is guaranteed to be recognized as a reset pin request. Shorter pulses are not guaranteed to override reset requests from internal sources.

<sup>3</sup> To enter BDM mode following a POR, BKGD/MS must be held low during the power-up and for a hold time of  $t_{\text{MSH}}$  after  $V_{\text{DD}}$  rises above  $V_{\text{LVD}}$ .

<sup>4</sup> This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

<sup>5</sup> Timing is shown with respect to 20%  $V_{\text{DD}}$  and 80%  $V_{\text{DD}}$  levels. Temperature range  $-40^\circ\text{C}$  to  $85^\circ\text{C}$ .

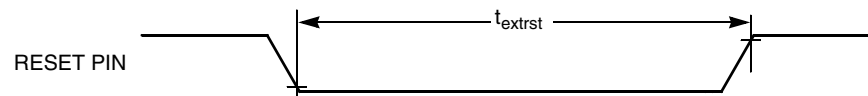
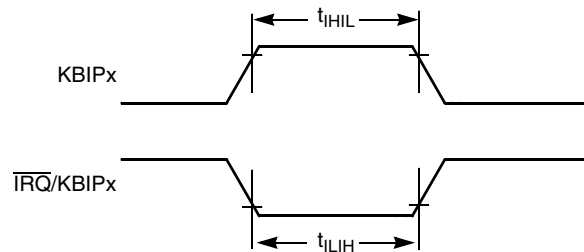


Figure 13. Reset Timing

Figure 14.  $\overline{\text{IRQ}}/\text{KBIPx}$  Timing

### 3.10.2 TPM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 13. TPM Input Timing

No.	C	Function	Symbol	Min	Max	Unit
1	D	External clock frequency	$f_{TCLK}$	0	$f_{Bus}/4$	Hz
2	D	External clock period	$t_{TCLK}$	4	—	$t_{cyc}$
3	D	External clock high time	$t_{clkh}$	1.5	—	$t_{cyc}$
4	D	External clock low time	$t_{clkl}$	1.5	—	$t_{cyc}$
5	D	Input capture pulse width	$t_{ICPW}$	1.5	—	$t_{cyc}$

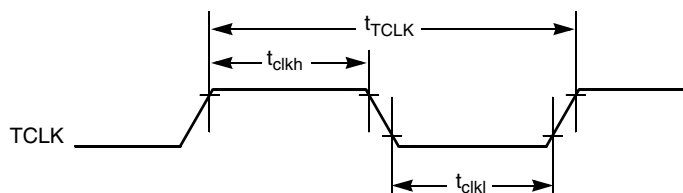


Figure 15. Timer External Clock

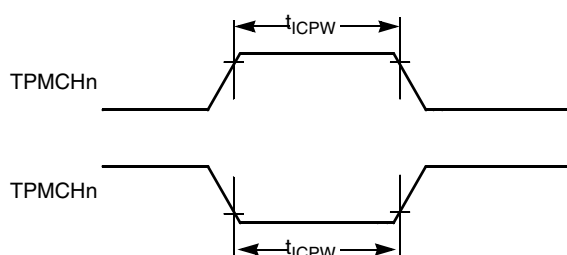


Figure 16. Timer Input Capture Pulse

### 3.10.3 SPI Timing

Table 14 and Figure 17 through Figure 20 describe the timing requirements for the SPI system.

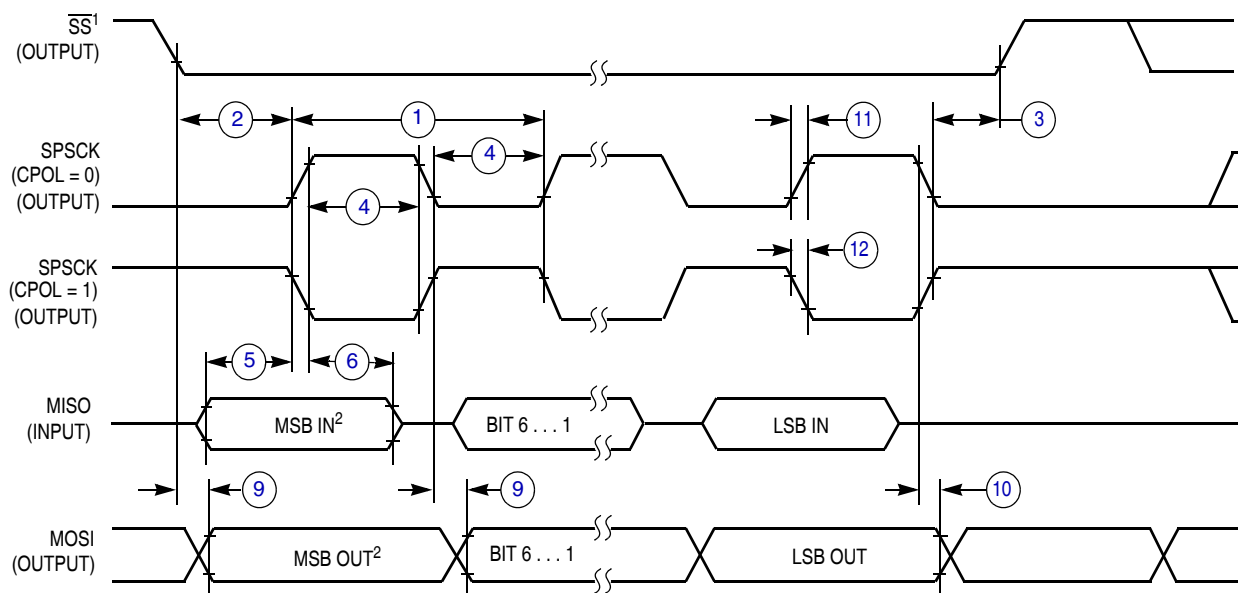
Table 14. SPI Timing

No.	C	Function	Symbol	Min	Max	Unit
—	D	Operating frequency Master Slave	$f_{op}$	$f_{Bus}/2048$ 0	$f_{Bus}/2^1$ $f_{Bus}/4$	Hz
1	D	SPSCK period Master Slave	$t_{SPSCK}$	2 4	2048 —	$t_{cyc}$ $t_{cyc}$
2	D	Enable lead time Master Slave	$t_{Lead}$	1/2 1	— —	$t_{SPSCK}$ $t_{cyc}$
3	D	Enable lag time Master Slave	$t_{Lag}$	1/2 1	— —	$t_{SPSCK}$ $t_{cyc}$

Table 14. SPI Timing (continued)

No.	C	Function	Symbol	Min	Max	Unit
4	D	Clock (SPSCK) high or low time Master Slave	$t_{WSPSCK}$	$t_{cyc} - 30$ $t_{cyc} - 30$	$1024 t_{cyc}$ —	ns ns
5	D	Data setup time (inputs) Master Slave	$t_{SU}$	15 15	— —	ns ns
6	D	Data hold time (inputs) Master Slave	$t_{HI}$	0 25	— —	ns ns
7	D	Slave access time	$t_a$	—	1	$t_{cyc}$
8	D	Slave MISO disable time	$t_{dis}$	—	1	$t_{cyc}$
9	D	Data valid (after SPSCK edge) Master Slave	$t_v$	— —	25 25	ns ns
10	D	Data hold time (outputs) Master Slave	$t_{HO}$	0 0	— —	ns ns
11	D	Rise time Input Output	$t_{RI}$ $t_{RO}$	— —	$t_{cyc} - 25$ 25	ns ns
12	D	Fall time Input Output	$t_{FI}$ $t_{FO}$	— —	$t_{cyc} - 25$ 25	ns ns

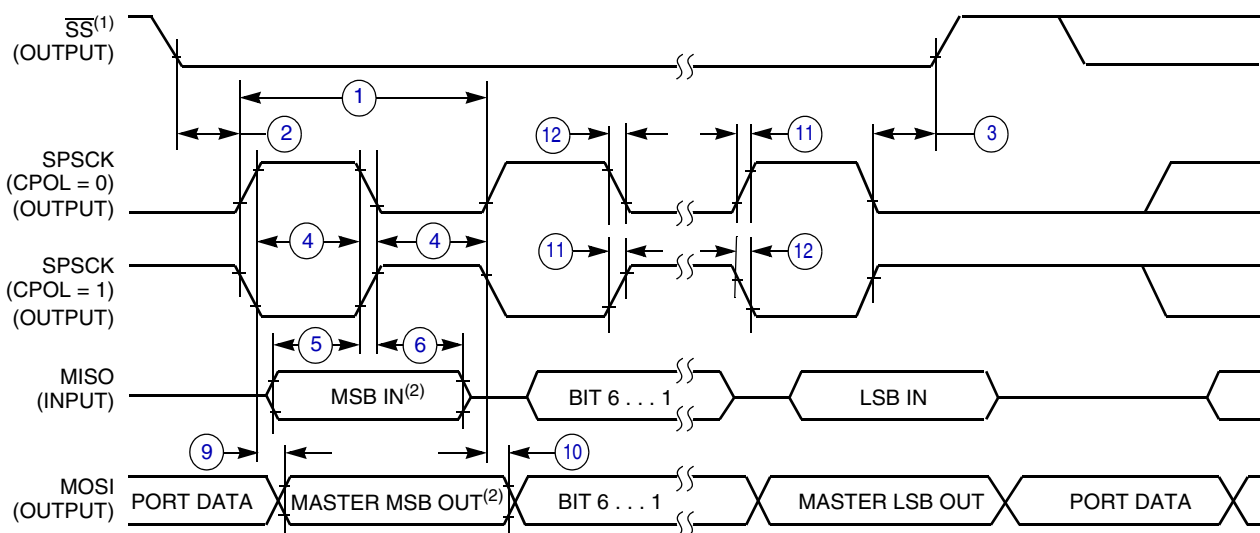
<sup>1</sup> Max operating frequency limited to 8MHz when input filter disabled and high output drive strength enabled. Max operating frequency limited to 5MHz when input filter enabled and high output drive strength disabled.



NOTES:

1.  $\overline{SS}$  output mode (DDS7 = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 17. SPI Master Timing (CPHA = 0)

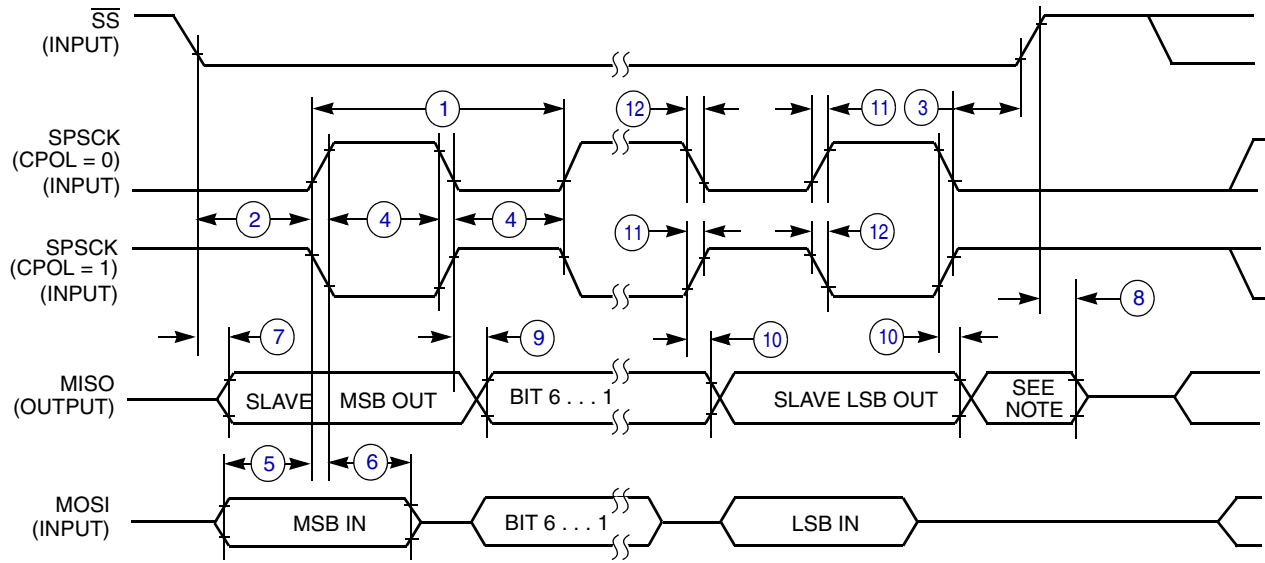


NOTES:

1.  $\overline{SS}$  output mode (DDS7 = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

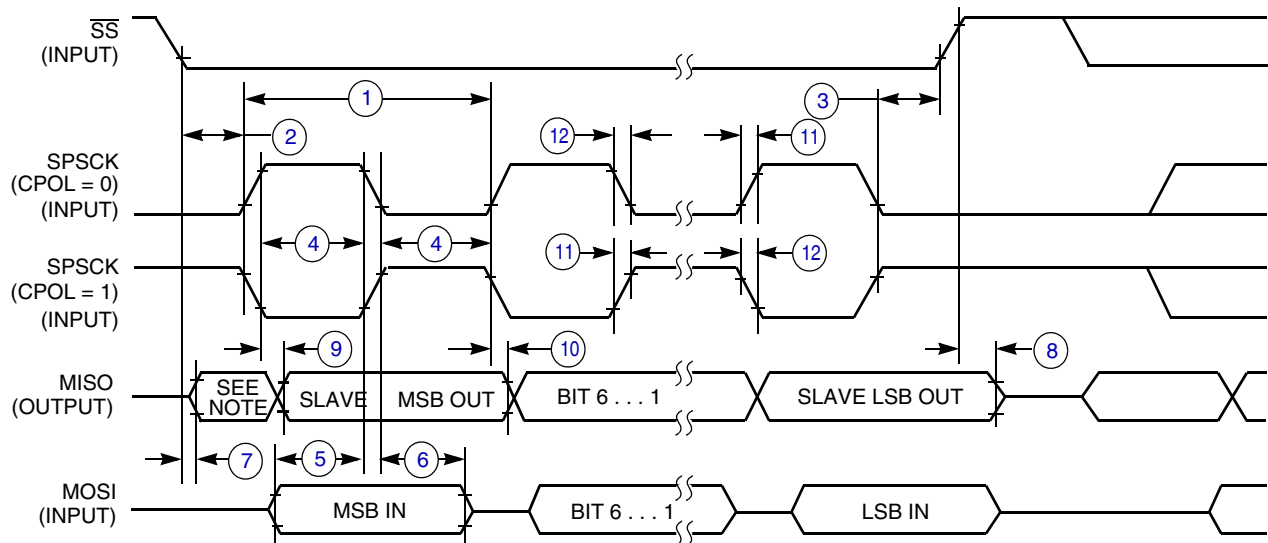
Figure 18. SPI Master Timing (CPHA = 1)





NOTE:

1. Not defined but normally MSB of character just received

**Figure 19. SPI Slave Timing (CPHA = 0)**

NOTE:

1. Not defined but normally LSB of character just received

**Figure 20. SPI Slave Timing (CPHA = 1)**

### 3.11 Analog Comparator (ACMP) Electricals

Table 15. Analog Comparator Electrical Specifications

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage	$V_{DD}$	1.8	—	3.6	V
P	Supply current (active)	$I_{DDAC}$	—	20	35	$\mu A$
D	Analog input voltage	$V_{AIN}$	$V_{SS} - 0.3$	—	$V_{DD}$	V
P	Analog input offset voltage	$V_{AIO}$		20	40	mV
C	Analog comparator hysteresis	$V_H$	3.0	9.0	15.0	mV
P	Analog input leakage current	$I_{ALKG}$	—	—	1.0	$\mu A$
C	Analog comparator initialization delay	$t_{AINIT}$	—	—	1.0	$\mu s$

### 3.12 ADC Characteristics

Table 16. 12-Bit ADC Operating Conditions

C	Characteristic	Conditions	Symbol	Min	Typical <sup>1</sup>	Max	Unit	Comment
D	Supply voltage	Absolute	$V_{DDAD}$	1.8	—	3.6	V	
		Delta to $V_{DD}$ ( $V_{DD} - V_{DDAD}$ ) <sup>2</sup>	$\Delta V_{DDAD}$	−100	0	100	mV	
D	Ground voltage	Delta to $V_{SS}$ ( $V_{SS} - V_{SSAD}$ ) <sup>2</sup>	$\Delta V_{SSAD}$	−100	0	100	mV	
D	Ref Voltage High		$V_{REFH}$	1.8	$V_{DDAD}$	$V_{DDAD}$	V	
D	Input Voltage		$V_{ADIN}$	$V_{REFL}$	—	$V_{REFH}$	V	
C	Input Capacitance		$C_{ADIN}$	—	4.5	5.5	pF	
C	Input Resistance		$R_{ADIN}$	—	5	7	k $\Omega$	
C	Analog Source Resistance	12 bit mode $f_{ADCK} > 4$ MHz $f_{ADCK} < 4$ MHz	$R_{AS}$	— —	— —	2 5	k $\Omega$	External to MCU
		10 bit mode $f_{ADCK} > 4$ MHz $f_{ADCK} < 4$ MHz		— —	— —	5 10		
		8 bit mode (all valid $f_{ADCK}$ )		—	—	10		
D	ADC Conversion Clock Freq.	High Speed (ADLPC=0)	$f_{ADCK}$	0.4	—	8.0	MHz	
		Low Power (ADLPC=1)		0.4	—	4.0		

<sup>1</sup> Typical values assume  $V_{DDAD} = 3.0$  V, Temp = 25 °C,  $f_{ADCK} = 1.0$  MHz unless otherwise state. Typical values are for reference only and are not tested in production.

<sup>2</sup> DC potential difference.

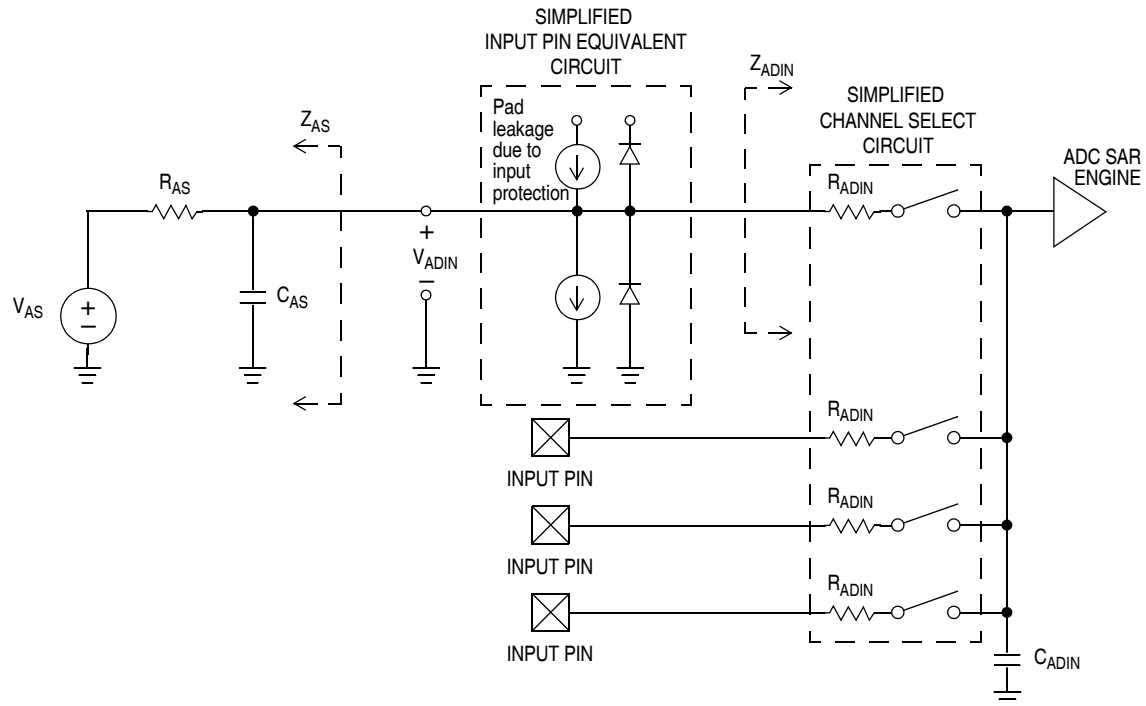


Figure 21. ADC Input Impedance Equivalency Diagram

Table 17. 12-Bit ADC Characteristics ( $V_{REFH} = V_{DDAD}$ ,  $V_{REFL} = V_{SSAD}$ )

C	Characteristic	Conditions	Symbol	Min	Typical <sup>1</sup>	Max	Unit	Comment
T	Supply Current ADLPC=1 ADLSMP=1 ADCO=1		$I_{DDAD}$	—	120	—	$\mu A$	
T	Supply Current ADLPC=1 ADLSMP=0 ADCO=1		$I_{DDAD}$	—	202	—	$\mu A$	
T	Supply Current ADLPC=0 ADLSMP=1 ADCO=1		$I_{DDAD}$	—	288	—	$\mu A$	
P	Supply Current ADLPC=0 ADLSMP=0 ADCO=1		$I_{DDAD}$	—	0.532	1	mA	
P	ADC Asynchronous Clock Source	High Speed (ADLPC=0)	$f_{ADACK}$	2	3.3	5	MHz	$t_{ADACK} = 1/f_{ADACK}$
P		Low Power (ADLPC=1)		1.25	2	3.3		

Table 17. 12-Bit ADC Characteristics ( $V_{REFH} = V_{DDAD}$ ,  $V_{REFL} = V_{SSAD}$ ) (continued)

C	Characteristic	Conditions	Symbol	Min	Typical <sup>1</sup>	Max	Unit	Comment
P	Conversion Time (Including sample time)	Short Sample (ADLSMP=0)	t <sub>ADC</sub>	—	20	—	ADCK cycles	See ADC chapter in the <i>QE32 Series MCU Reference Manual</i> for conversion time variances
C		Long Sample (ADLSMP=1)		—	40	—		
P	Sample Time	Short Sample (ADLSMP=0)	t <sub>ADS</sub>	—	3.5	—	ADCK cycles	
C		Long Sample (ADLSMP=1)		—	23.5	—		
T	Total Unadjusted Error	12 bit mode	E <sub>TUE</sub>	—	±3.0	—	LSB <sup>2</sup>	Includes quantization
P		10 bit mode		—	±1	±2.5		
T		8 bit mode		—	±0.5	±1.0		
T	Differential Non-Linearity	12 bit mode	DNL	—	±1.75	—	LSB <sup>2</sup>	
P		10 bit mode <sup>3</sup>		—	±0.5	±1.0		
T		8 bit mode <sup>3</sup>		—	±0.3	±0.5		
T	Integral Non-Linearity	12 bit mode	INL	—	±1.5	—	LSB <sup>2</sup>	
T		10 bit mode		—	±0.5	±1.0		
T		8 bit mode		—	±0.3	±0.5		
T	Zero-Scale Error	12 bit mode	E <sub>ZS</sub>	—	±1.5	—	LSB <sup>2</sup>	V <sub>ADIN</sub> = V <sub>SSAD</sub>
P		10 bit mode		—	±0.5	±1.5		
T		8 bit mode		—	±0.5	±0.5		
T	Full-Scale Error	12 bit mode	E <sub>FS</sub>	—	±1.0	—	LSB <sup>2</sup>	V <sub>ADIN</sub> = V <sub>DDAD</sub>
P		10 bit mode		—	±0.5	±1		
T		8 bit mode		—	±0.5	±0.5		
D	Quantization Error	12 bit mode	E <sub>Q</sub>	—	–1 to 0	—	LSB <sup>2</sup>	
		10 bit mode		—	—	±0.5		
		8 bit mode		—	—	±0.5		
D	Input Leakage Error	12 bit mode	E <sub>IL</sub>	—	±2	—	LSB <sup>2</sup>	Pad leakage <sup>4*</sup> R <sub>AS</sub>
		10 bit mode		—	±0.2	±4		
		8 bit mode		—	±0.1	±1.2		
D	Temp Sensor Slope	–40°C to 25°C	m	—	1.646	—	mV/°C	
		25°C to 85°C		—	1.769	—		
D	Temp Sensor Voltage	25°C	V <sub>TEMP25</sub>	—	701.2	—	mV	

<sup>1</sup> Typical values assume  $V_{DDAD} = 3.0$  V, Temp = 25 °C,  $f_{ADCK} = 1.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

$$^2 \text{ 1 LSB} = (V_{\text{REFH}} - V_{\text{REFL}})/2^N$$

<sup>3</sup> Monotonicity and No-Missing-Codes guaranteed in 10 bit and 8 bit modes

<sup>4</sup> Based on input pad leakage current. Refer to pad electricals.

### 3.13 Flash Specifications

This section provides details about program/erase times and program-erase endurance for flash memory.

Program and erase operations do not require any special power sources other than the normal  $V_{\text{DD}}$  supply. For more detailed information about program/erase operations, see MC9S08QE32 Series Reference Manual Chapter 4 Memory.

**Table 18. Flash Characteristics**

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage for program/erase –40°C to 85°C	$V_{\text{prog/erase}}$	1.8	—	3.6	V
D	Supply voltage for read operation	$V_{\text{Read}}$	1.8	—	3.6	V
D	Internal FCLK frequency <sup>1</sup>	$f_{\text{FCLK}}$	150	—	200	kHz
D	Internal FCLK period (1/FCLK)	$t_{\text{Fcyc}}$	5	—	6.67	μs
P	Byte program time (random location) <sup>(2)</sup>	$t_{\text{prog}}$	9			$t_{\text{Fcyc}}$
P	Byte program time (burst mode) <sup>(2)</sup>	$t_{\text{Burst}}$	4			$t_{\text{Fcyc}}$
P	Page erase time <sup>2</sup>	$t_{\text{Page}}$	4000			$t_{\text{Fcyc}}$
P	Mass erase time <sup>(2)</sup>	$t_{\text{Mass}}$	20,000			$t_{\text{Fcyc}}$
	Byte program current <sup>3</sup>	$R_{\text{IDDBP}}$	—	4	—	mA
	Page erase current <sup>3</sup>	$R_{\text{IDDPE}}$	—	6	—	mA
C	Program/erase endurance <sup>4</sup> $T_L$ to $T_H$ = –40°C to 85°C $T = 25^\circ\text{C}$		10,000	— 100,000	— —	cycles
C	Data retention <sup>5</sup>	$t_{\text{D-ret}}$	15	100	—	years

<sup>1</sup> The frequency of this clock is controlled by software setting.

<sup>2</sup> These values are hardware state machine controlled. User code does not need to count cycles. This information is supplied for calculating approximate time to program and erase.

<sup>3</sup> The program and erase currents are additional to the standard run  $I_{\text{DD}}$ . These values are measured at room temperatures with  $V_{\text{DD}} = 3.0$  V, bus frequency = 4.0 MHz.

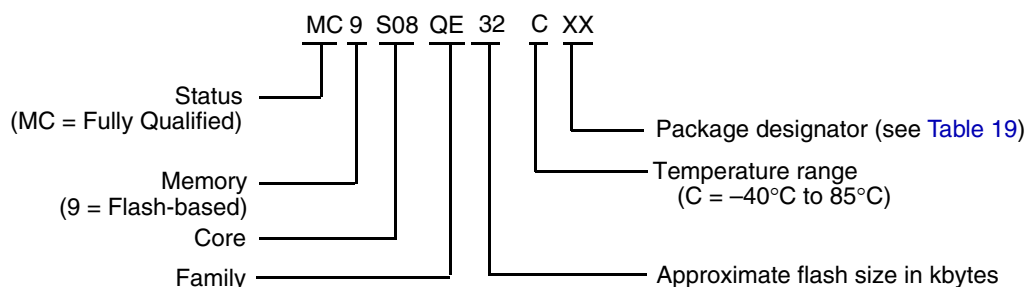
<sup>4</sup> **Typical endurance for flash** was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale defines typical endurance, please refer to Engineering Bulletin EB619, *Typical Endurance for Nonvolatile Memory*.

<sup>5</sup> **Typical data retention** values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25°C using the Arrhenius equation. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618, *Typical Data Retention for Nonvolatile Memory*.

## 4 Ordering Information

This section contains ordering information for the MC9S08QE32 series of MCUs.

Example of the device numbering system:



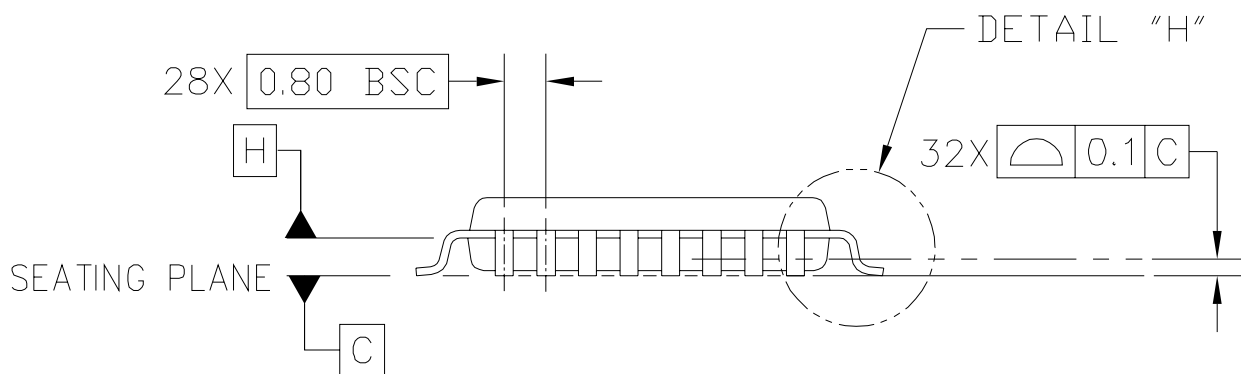
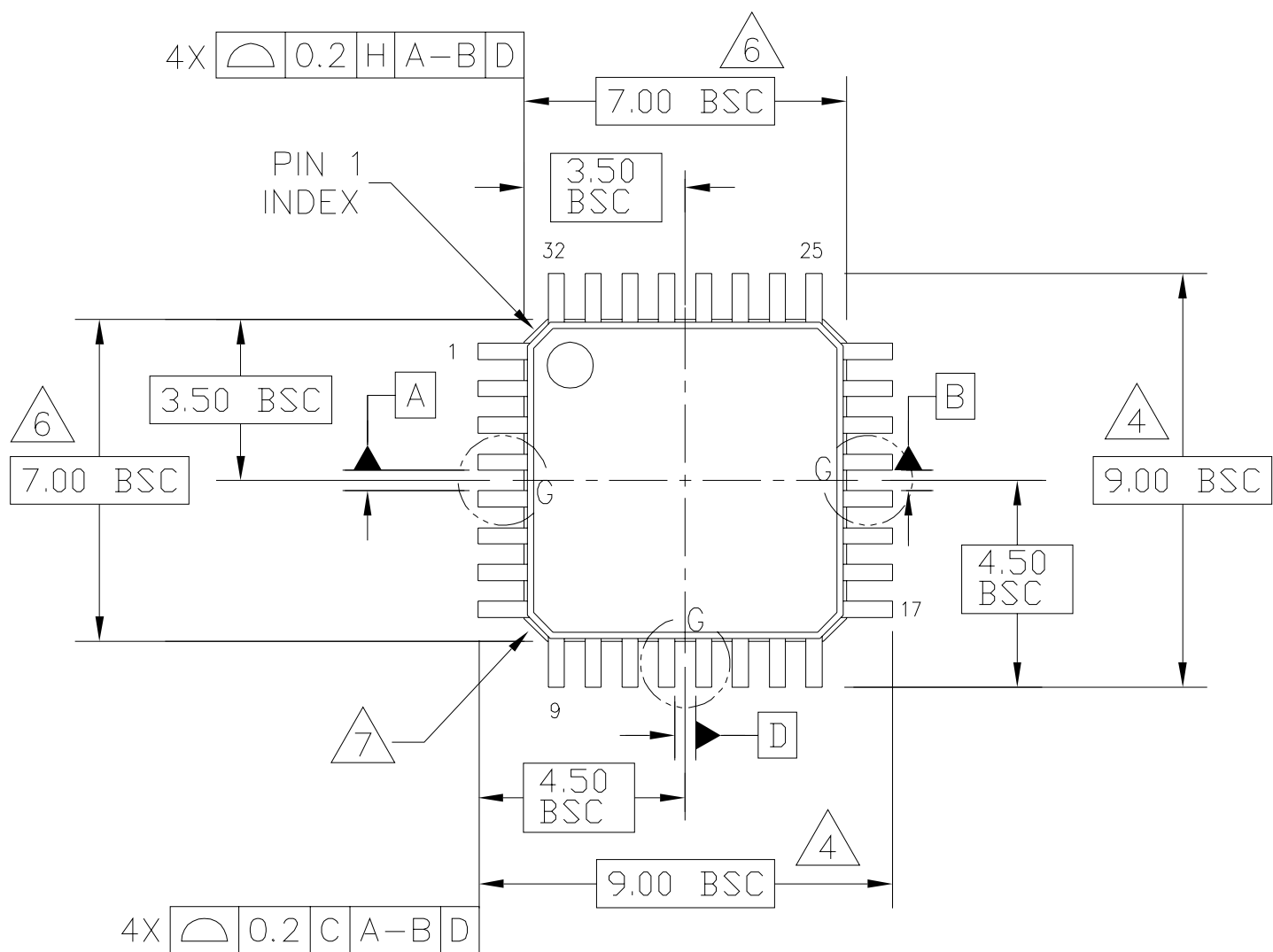
## 5 Package Information

Table 19. Package Descriptions

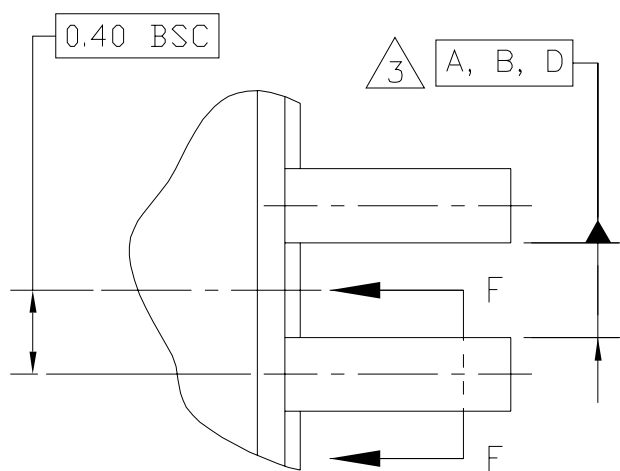
Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
48	Quad Flat No-Leads	QFN	FT	1314	98ARH99048A
44	Low Quad Flat Package	LQFP	LD	824D	98ASS23225W
32	Low Quad Flat Package	LQFP	LC	873A	98ASH70029A
28	Small Outline Integrated Circuit	SOIC	WL	751F	98ASB42345B

### 5.1 Mechanical Drawings

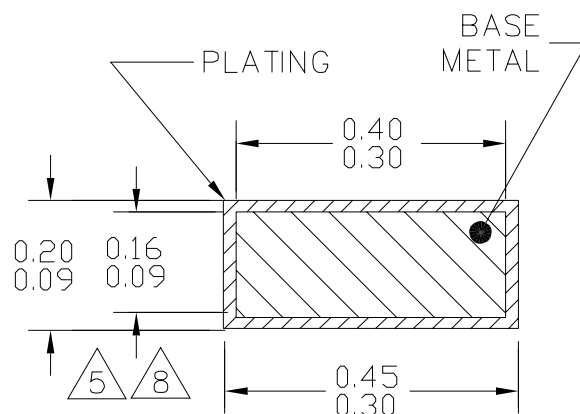
The following pages are mechanical drawings for the packages described in Table 19. For the latest available drawings please visit our web site (<http://www.freescale.com>) and enter the package's document number into the keyword search box.



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TITLE: LOW PROFILE QUAD FLAT PACK (LQFP) 32 LEAD, 0.8 PITCH (7 X 7 X 1.4)	DOCUMENT NO: 98ASH70029A		REV: D
	CASE NUMBER: 873A-03		19 MAY 2005
	STANDARD: JEDEC MS-026 BBA		

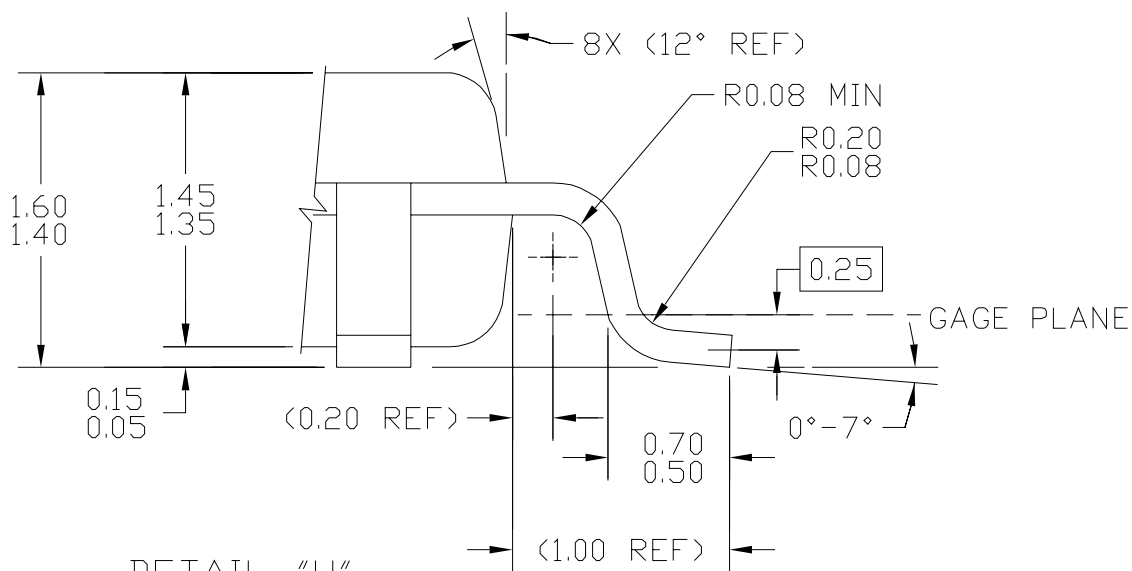


DETAIL G



$\Phi$  0.2  $\textcircled{M}$  C A-B D

SECTION F-F  
ROTATED 90°CW  
32 PLACES



DETAIL "H"

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TITLE: LOW PROFILE QUAD FLAT PACK (LQFP) 32 LEAD, 0.8 PITCH (7 X 7 X 1.4)	DOCUMENT NO: 98ASH70029A		REV: D
	CASE NUMBER: 873A-03		19 MAY 2005
	STANDARD: JEDEC MS-026 BBA		



NOTES:

1. DIMENSIONS ARE IN MILLIMETERS.

2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5-1994.

3. DATUMS A, B, AND D TO BE DETERMINED AT DATUM PLANE H.

4. DIMENSIONS TO BE DETERMINED AT SEATING PLANE DATUM C.

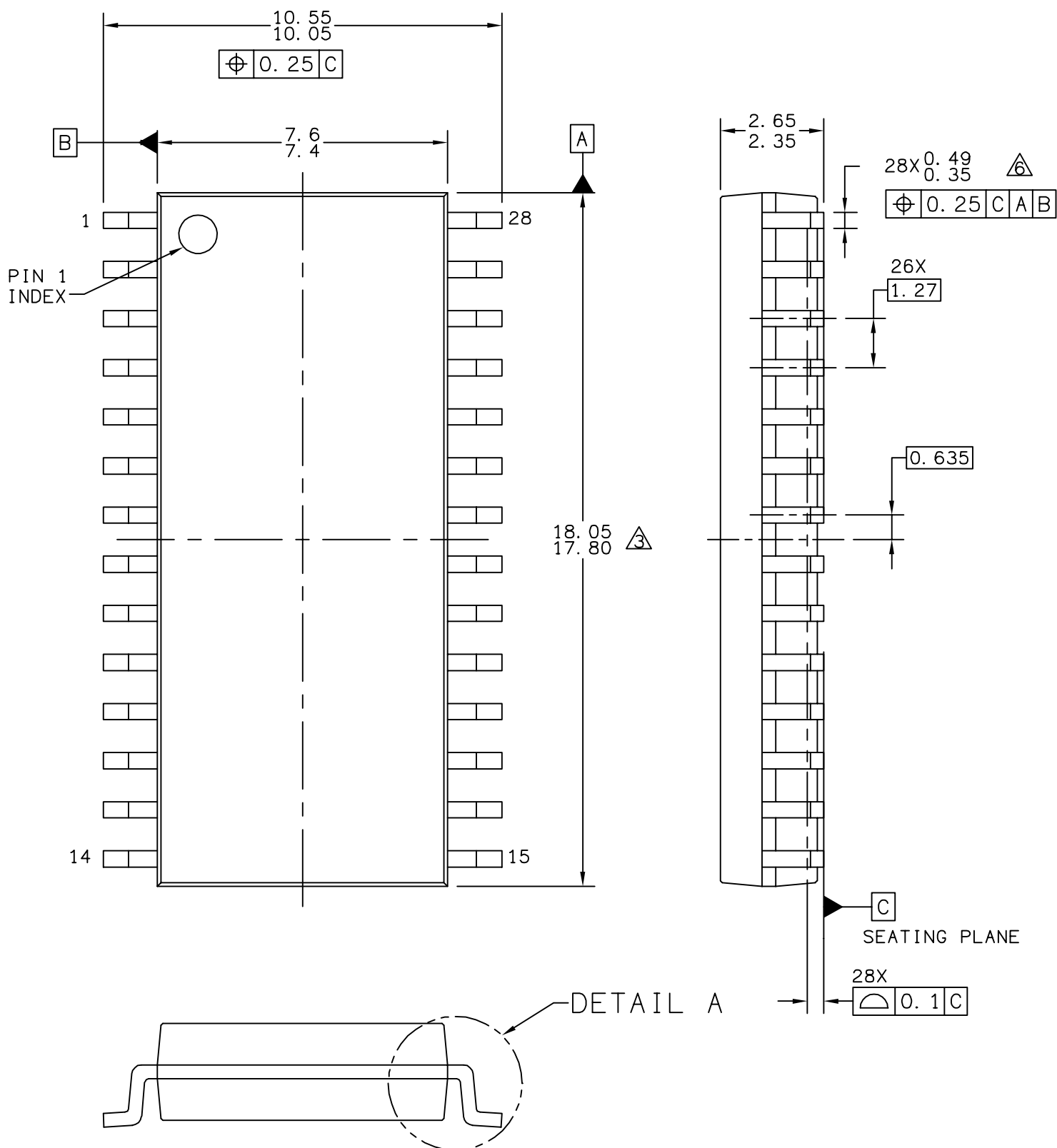
5. DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE MAXIMUM DIMENSION BY MORE THAN 0.08 MM. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD OR PROTRUSION: 0.07 MM.

6. DIMENSIONS DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 MM PER SIDE. DIMENSIONS ARE MAXIMUM PLASTIC BODY SIZE DIMENSIONS INCLUDING MOLD MISMATCH.

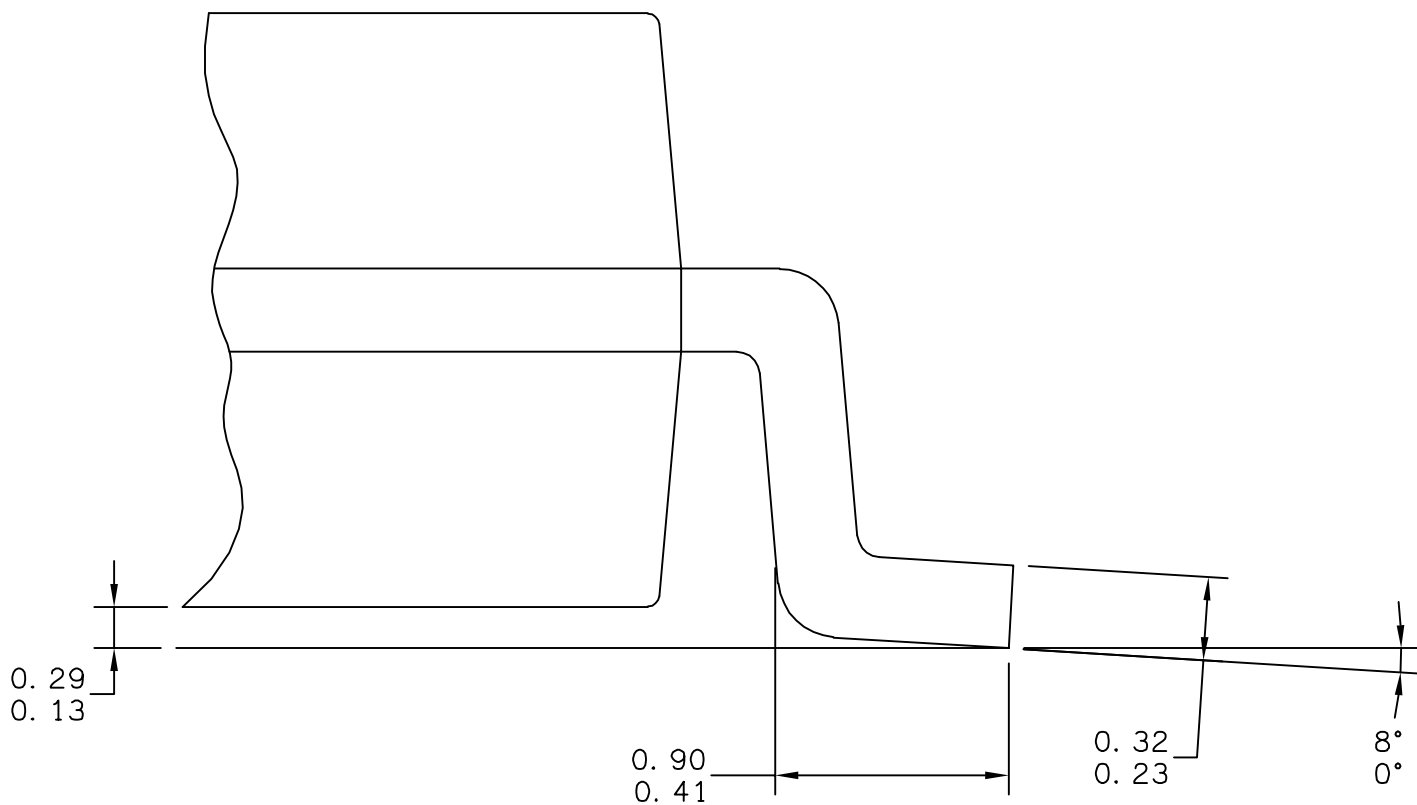
7. EXACT SHAPE OF EACH CORNER IS OPTIONAL.

8. THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.1 MM AND 0.25 MM FROM THE LEAD TIP.

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TITLE: LOW PROFILE QUAD FLAT PACK (LQFP) 32 LEAD, 0.8 PITCH (7 X 7 X 1.4)	DOCUMENT NO: 98ASH70029A		REV: D
	CASE NUMBER: 873A-03		19 MAY 2005
	STANDARD: JEDEC MS-026 BBA		



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TITLE: SOIC, WIDE BODY, 28 LEAD CASEOUTLINE	DOCUMENT NO: 98ASB42345B		REV: G
	CASE NUMBER: 751F-05		10 MAR 2005
	STANDARD: MS-013AE		



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# MECHANICAL OUTLINE

PRINT VERSION NOT TO SCALE

TITLE: SOIC, WIDE BODY,  
28 LEAD  
CASEOUTLINE

DOCUMENT NO: 98ASB42345B

REV: G

CASE NUMBER: 751F-05

10 MAR 2005

STANDARD: MS-013AE

NOTES:

1. DIMENSIONS ARE IN MILLIMETERS.

2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.

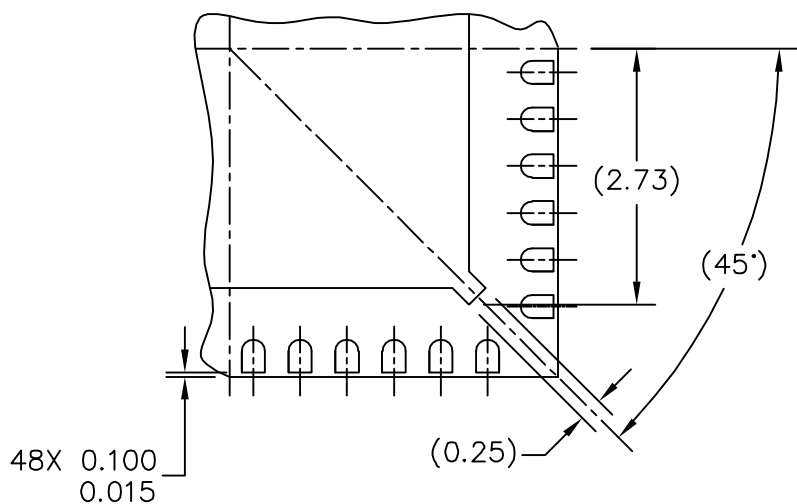
△3. THIS DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.

4. 751F-01 THRU -04 OBSOLETE. NEW STANDARD: 751F-05

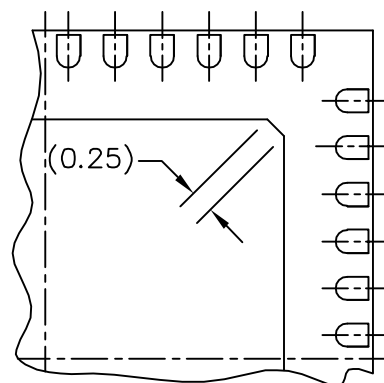
△5. THIS DIMENSION DOES NOT INCLUDE DAM BAR PROTRUSION ALLOWABLE DAM BAR PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF THIS DIMENSION AT MAXIMUM MATERIAL CONDITION.

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TITLE: SOIC, WIDE BODY, 28 LEAD CASEOUTLINE		DOCUMENT NO: 98ASB42345B		REV: G	
		CASE NUMBER: 751F-05		10 MAR 2005	
		STANDARD: MS-013AE			

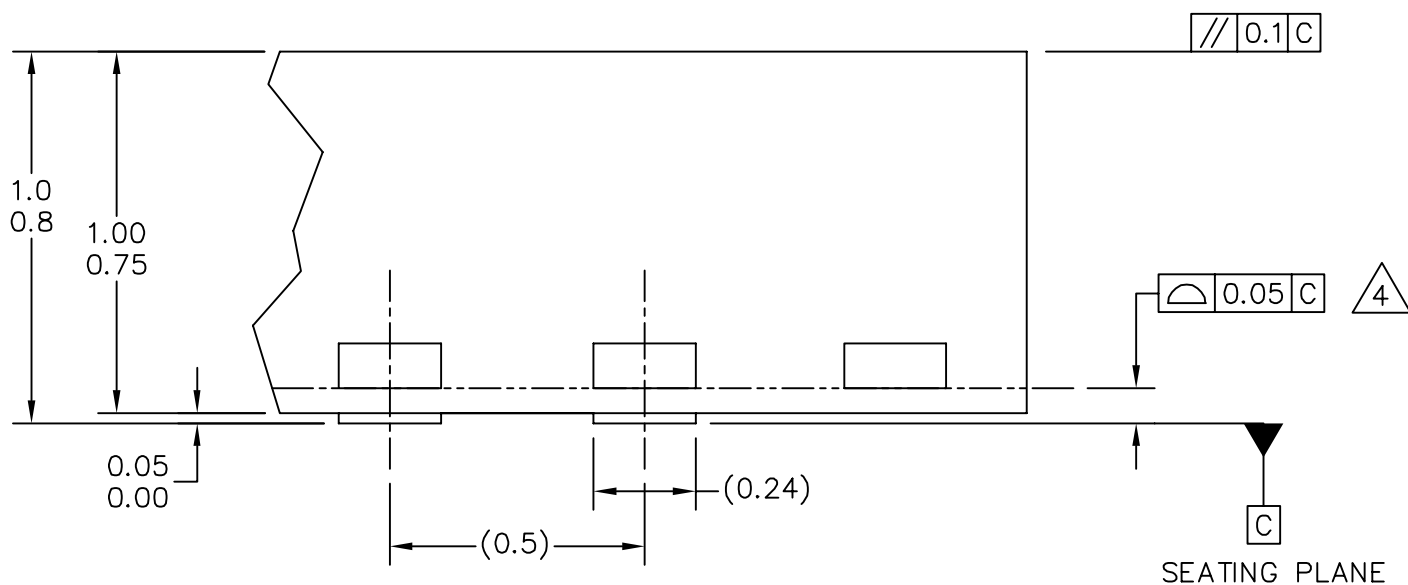




DETAIL N  
PREFERRED CORNER CONFIGURATION

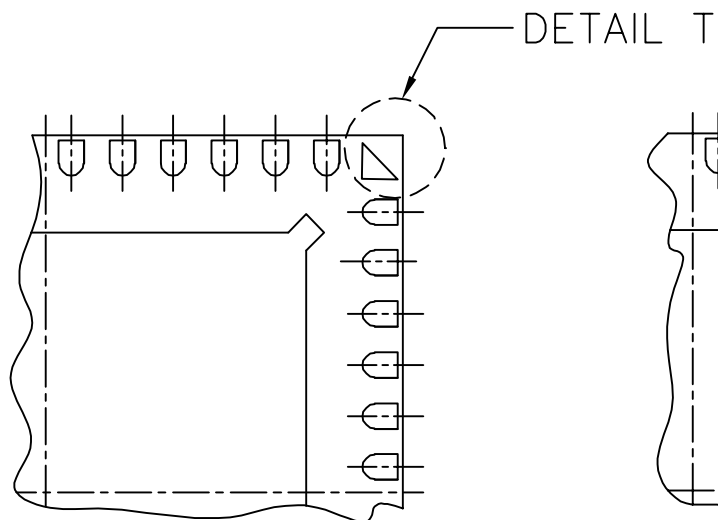


DETAIL M  
PREFERRED PIN 1 BACKSIDE IDENTIFIER

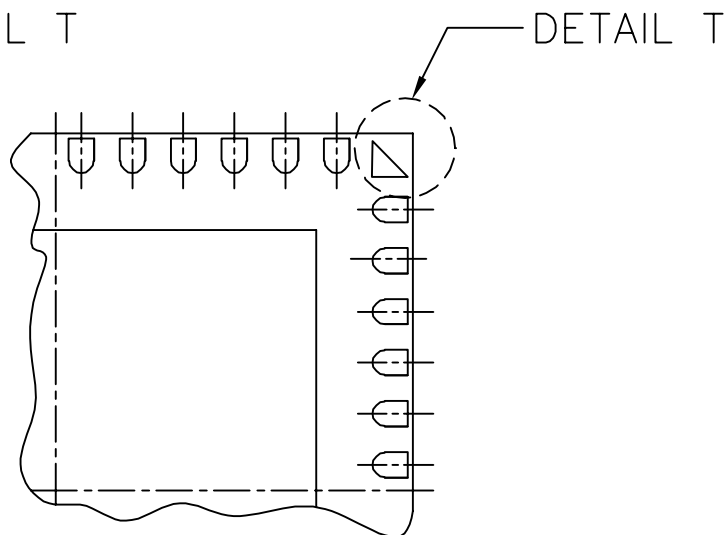


DETAIL G  
VIEW ROTATED 90° CW

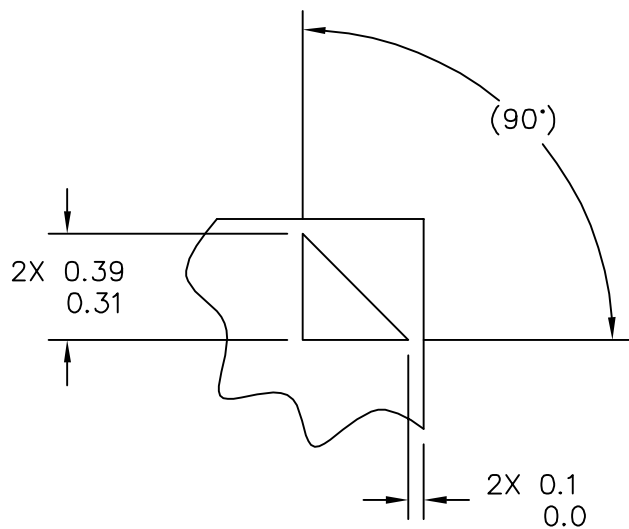
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TITLE: THERMALLY ENHANCED QUAD FLAT NON-LEADED PACKAGE (QFN) 48 TERMINAL, 0.5 PITCH (7 X 7 X 1)	DOCUMENT NO: 98ARH99048A		REV: F
	CASE NUMBER: 1314-05		05 DEC 2005
	STANDARD: JEDEC-MO-220 VKKD-2		



DETAIL M  
PIN 1 BACKSIDE IDENTIFIER OPTION




DETAIL M  
PIN 1 BACKSIDE IDENTIFIER OPTION



DETAIL T

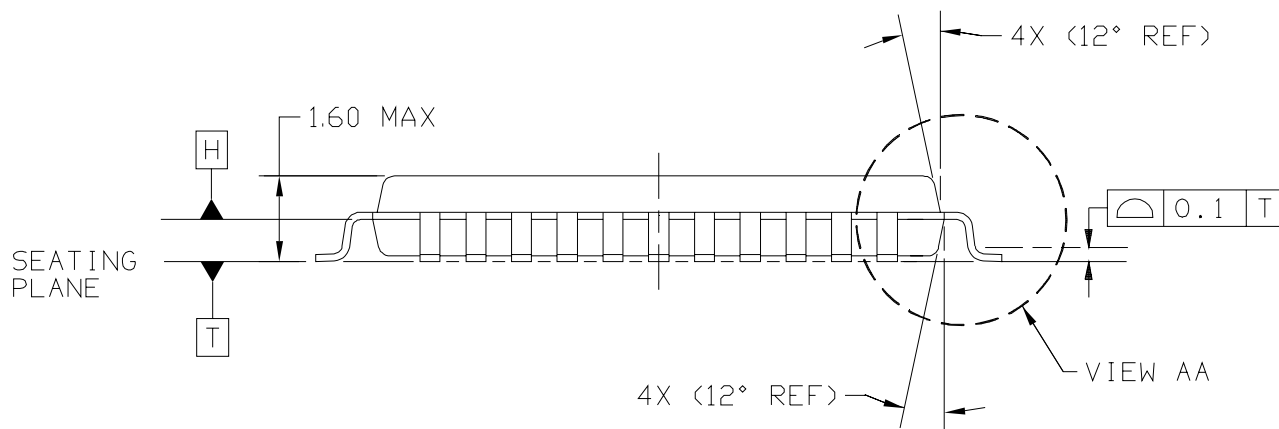
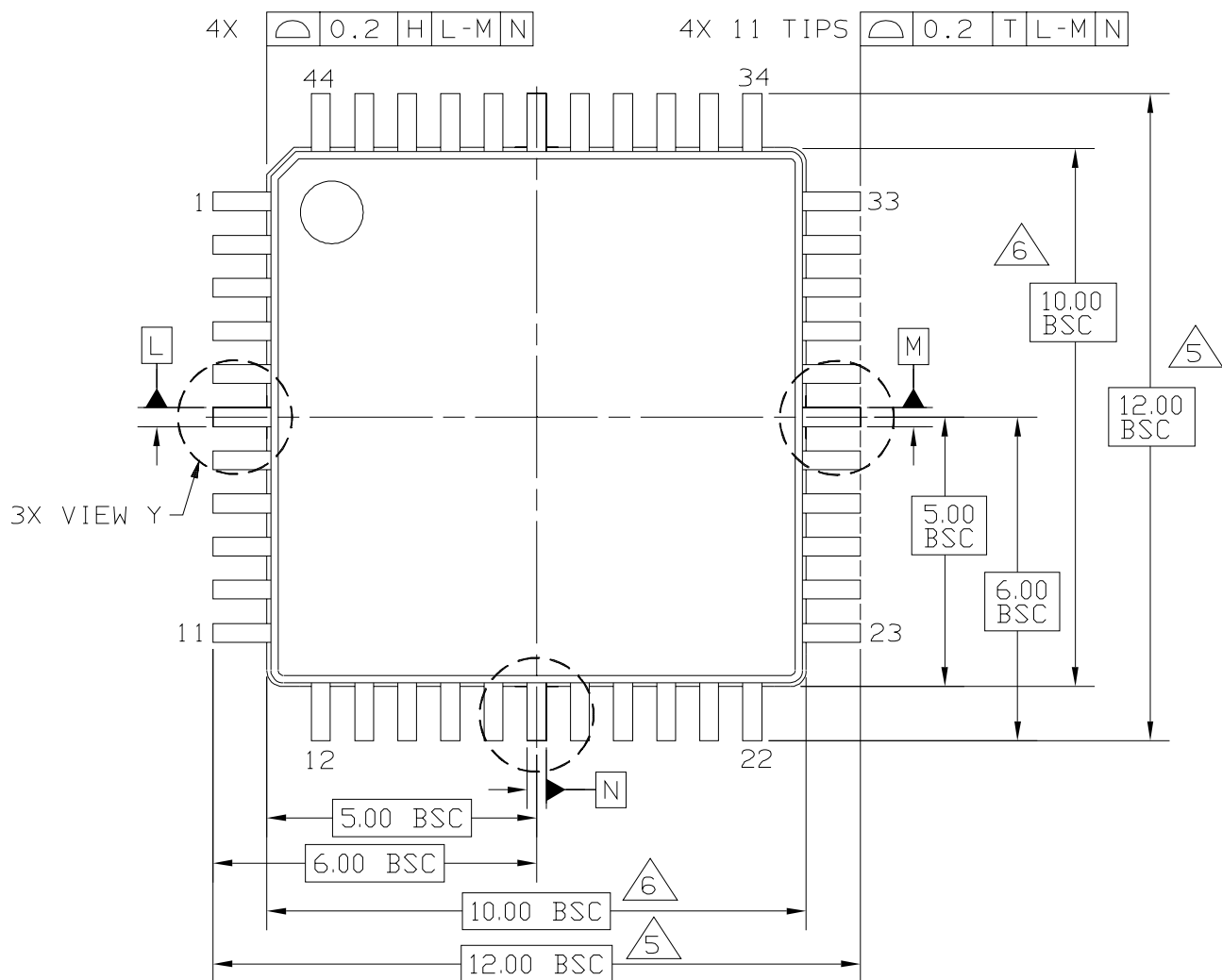
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TITLE: THERMALLY ENHANCED QUAD FLAT NON-LEADED PACKAGE (QFN) 48 TERMINAL, 0.5 PITCH (7 X 7 X 1)	DOCUMENT NO: 98ARH99048A		REV: F
	CASE NUMBER: 1314-05		05 DEC 2005
	STANDARD: JEDEC-MO-220 VKKD-2		

NOTES:

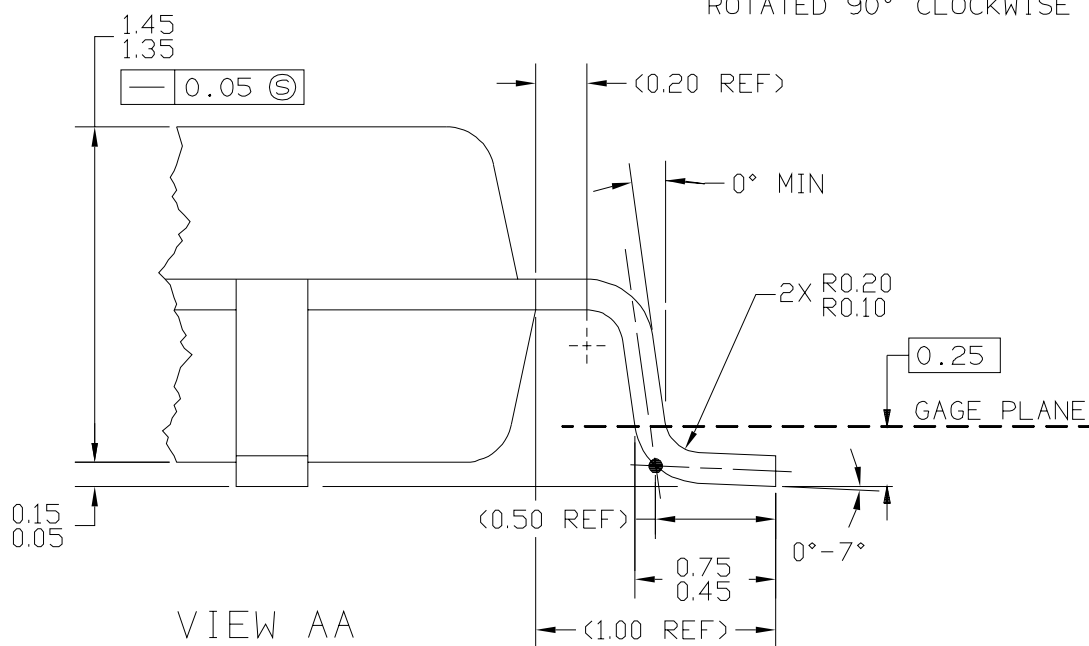
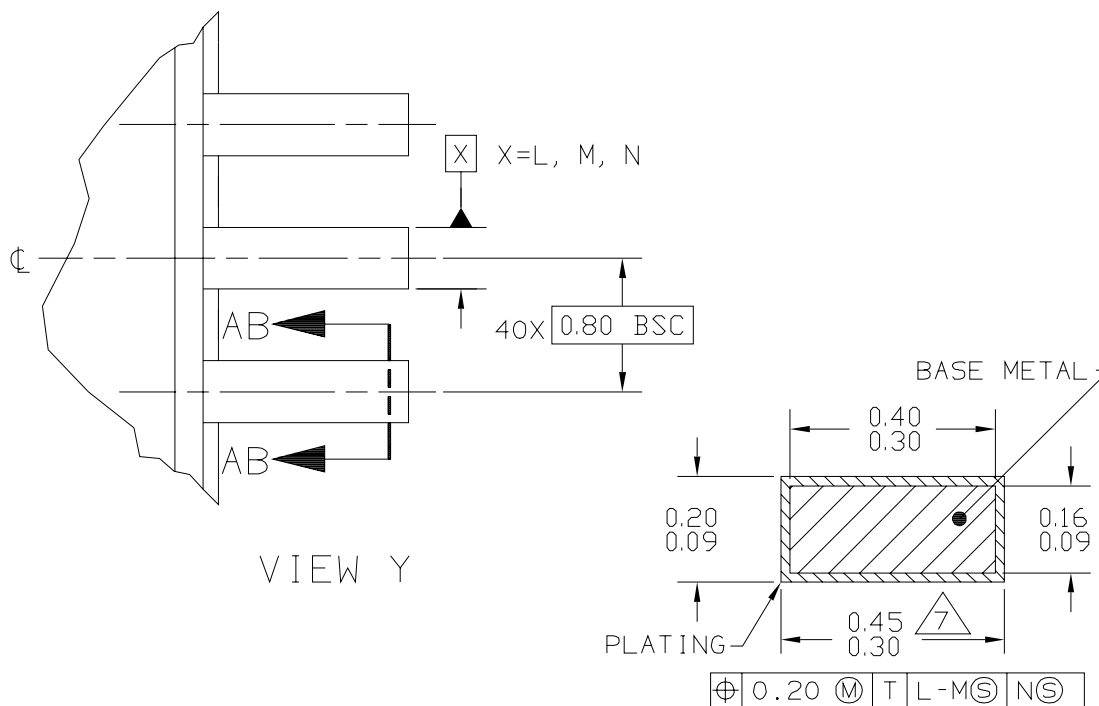
1. DIMENSIONS ARE IN MILLIMETERS.
2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M-1994.
3. THE COMPLETE JEDEC DESIGNATOR FOR THIS PACKAGE IS: HF-PQFN.
4.  COPLANARITY APPLIES TO LEADS, CORNER LEADS, AND DIE ATTACH PAD.
5. MIN METAL GAP SHOULD BE 0.2MM.

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TITLE: THERMALLY ENHANCED QUAD FLAT NON-LEADED PACKAGE (QFN) 48 TERMINAL, 0.5 PITCH (7 X 7 X 1)	DOCUMENT NO: 98ARH99048A		REV: F	
	CASE NUMBER: 1314-05		05 DEC 2005	
	STANDARD: JEDEC-MO-220 VKKD-2			





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TITLE:  44 LD LQFP, 10 X 10 PKG, 0.8 PITCH, 1.4 THICK	DOCUMENT NO: 98ASS23225W		REV: D
	CASE NUMBER: 824D-02		26 FEB 2007
	STANDARD: JEDEC MS-026-BCB		



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TITLE: 44 LD LQFP, 10 X 10 PKG, 0.8 PITCH, 1.4 THICK	DOCUMENT NO: 98ASS23225W		REV: D
	CASE NUMBER: 824D-02		26 FEB 2007
	STANDARD: JEDEC MS-026 BCB		

NOTES:

1. DIMENSIONS AND TOLERANCING PER ASME Y14.5M-1994.
2. CONTROLLING DIMENSION: MILLIMETER
3. DATUM PLANE H IS LOCATED AT BOTTOM OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.
4. DATUMS L, M AND N TO BE DETERMINED AT DATUM PLANE H.

△5. DIMENSIONS TO BE DETERMINED AT SEATING PLANE T.

△6. DIMENSIONS DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 PER SIDE. DIMENSIONS DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE H.

△7. DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. DAMBAR PROTRUSION SHALL NOT CAUSE THE DIMENSION TO EXCEED 0.53. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD OR PROTRUSION 0.07.

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TITLE: 44 LD LQFP, 10 X 10 PKG, 0.8 PITCH, 1.4 THICK	DOCUMENT NO: 98ASS23225W		REV: D
	CASE NUMBER: 824D-02		26 FEB 2007
	STANDARD: JEDEC MS-026 BCB		





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Rev. 3

11/2008

